

Lipschitz regularity of the eigenfunctions on optimal domains

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Abstract

We study the optimal sets $\Omega^* \subset \mathbb{R}^d$ for spectral functionals $F(\lambda_1(\Omega), \dots, \lambda_p(\Omega))$, which are bi-Lipschitz with respect to each of the eigenvalues $\lambda_1(\Omega), \dots, \lambda_p(\Omega)$ of the Dirichlet Laplacian on Ω , a prototype being the problem

$$\min \{ \lambda_1(\Omega) + \dots + \lambda_p(\Omega) : \Omega \subset \mathbb{R}^d, |\Omega| = 1 \}.$$

We prove the Lipschitz regularity of the eigenfunctions u_1, \dots, u_p of the Dirichlet Laplacian on the optimal set Ω^* and, as a corollary, we deduce that Ω^* is open. For functionals depending only on a generic subset of the spectrum, as for example $\lambda_k(\Omega)$ or $\lambda_{k_1}(\Omega) + \dots + \lambda_{k_p}(\Omega)$, our result proves only the existence of a Lipschitz continuous eigenfunction in correspondence to each of the eigenvalues involved.

1 Introduction

In this paper we study the domains of prescribed volume, which are optimal for functionals depending on the spectrum of the Dirichlet Laplacian. Precisely, we consider shape optimization problems of the form

$$\min \left\{ F(\lambda_1(\Omega), \dots, \lambda_p(\Omega)) : \Omega \subset \mathbb{R}^d, |\Omega| = 1 \right\}, \quad (1.1)$$

where $F : \mathbb{R}^p \rightarrow \mathbb{R}$ is a given continuous function, increasing in each variable, and $\lambda_k(\Omega)$, for $k = 1, \dots, p$, denotes the k^{th} eigenvalue of the Dirichlet Laplacian on Ω , i.e. the k^{th} element of the spectrum¹ of the Dirichlet Laplacian.

The optimization problems of the form (1.1) naturally arise in the study of physical phenomena as, for example, heat diffusion or wave propagation inside a domain $\Omega \subset \mathbb{R}^d$. Despite of their simple formulation, these problems turn out to be quite challenging and their analysis usually depends on sophisticated variational techniques. Even the question of the existence of a minimizer for the simplest spectral optimization problem

$$\min \left\{ \lambda_k(\Omega) : \Omega \subset \mathbb{R}^d, |\Omega| = 1 \right\}, \quad (1.2)$$

was answered only recently for general $k \in \mathbb{N}$ (see [7] and [24]). This question was first formulated in the 19th century by Lord Rayleigh in his treatise *The Theory of Sound* [27] and it was related to the specific case $k = 1$. It was proved only in the 1920s by Faber and Krahn that the minimizer in this case is the ball. From this result one can easily deduce

¹We recall that due to the volume constraint $|\Omega| = 1$ the Dirichlet Laplacian on Ω has compact resolvent and its spectrum is discrete.

the Krahn-Szegö inequality, which states that a union of two disjoint balls is optimal for (1.2) with $k = 2$, i.e. it has the smaller second eigenvalue λ_2 among all sets of prescribed measure. An explicit construction of an optimal set for higher eigenvalues is an extremely difficult task. Balls are not always optimal, in fact it was proved by Keller and Wolf in 1994 (see [28]) that a union of disjoint balls is not optimal for λ_{13} in two dimensions. It was recently proved by Berger and Oudet² that the later result holds for all $k \in \mathbb{N}$ large enough, which confirmed the previous numerical results obtained in [25] and [3].

The classical variational approach of proving existence and regularity of minimizers failed to provide a solution to the spectral problems (1.1) until the 1990s, the main reason being the lack of an appropriate topology on the space of domains $\Omega \subset \mathbb{R}^d$. A suitable convergence called γ -convergence was introduced by Dal Maso and Mosco (see [15, 16]) in the 1980s and was used by Buttazzo and Dal Maso (see [13]) for proving in 1993 a very general existence result for (1.1), under the additional constraint $\Omega \subset D$. The presence of the open bounded set $D \subset \mathbb{R}^d$ as a geometric obstacle (a *box*) provided the necessary compactness, needed to obtain the existence of an optimal domain in the class of *quasi-open*³ sets. The proof of existence of a quasi-open minimizer for (1.2) and, more generally, of (1.1) in the entire space \mathbb{R}^d was concluded in 2011 with the independent results of Bucur (see [7]) and Mazzoleni and Pratelli (see [24]). Moreover, it was proved that the optimal sets are bounded (see [7] and [22]) and of finite perimeter (see [7]).

The regularity of the optimal sets or the corresponding eigenfunctions turned out to be quite difficult question, due to the min-max nature of the spectral cost functionals, and is an open problem since the general Buttazzo-Dal Maso existence theorem. The only result that provides the complete regularity of the free boundary $\partial\Omega$ of the optimal set Ω concerns only the minimizers of (1.2)⁴ in the special case $k = 1$ and is due to Briançon and Lamboley ([5]) who proved that the free boundary of the optimal sets is smooth. The implementation of this result for higher eigenvalues presents some major difficulties since the techniques, developed by Alt and Caffarelli in [1], used in the proof are exclusive for functionals defined through a minimization and not min-max procedure on the Sobolev space $H_0^1(\Omega)$.

In this paper we study the regularity of the eigenfunctions (or state functions) on the optimal set Ω^* for the problem (1.2). Our main tool is a result proved by Briançon, Hayouni and Pierre ([6]), inspired by the pioneering work of Alt and Caffarelli (see [1]) on the regularity for a free boundary problem. It states that a function $u \in H^1(\mathbb{R}^d)$, satisfying an elliptic PDE on the set $\Omega = \{|u| > 0\}$, is Lipschitz continuous on the whole \mathbb{R}^d , if it satisfies the following *quasi-minimality* property:

$$\int_{\mathbb{R}^d} |\nabla u|^2 dx \leq \int_{\mathbb{R}^d} |\nabla v|^2 dx + cr^d, \quad \forall v \in H^1(\mathbb{R}^d) \text{ s.t. } u = v \text{ on } \mathbb{R}^d \setminus B_r(x), \quad (1.3)$$

for every ball $B_r(x) \subset \mathbb{R}^d$.

Since the variational characterization of the eigenvalue λ_k is given through a min-max procedure the transfer of the minimality properties of Ω to an eigenfunction u_k is a non-trivial task. In fact, it can be proved that the eigenfunction u_k is a quasi-minimizer in the sense of (1.3), provided that the eigenvalue $\lambda_k(\Omega^*)$ is simple. Since the latter is expected not to be true in general, we use an approximation procedure with sets Ω_ε , which are solutions of a spectral optimization problems of the form

$$\min \left\{ (1 - \varepsilon)\lambda_k(\Omega) + \varepsilon\lambda_{k-1}(\Omega) + c|\Omega| : \Omega^* \subset \Omega \subset \mathbb{R}^d \right\}.$$

²private communication

³A quasi-open set is a level set $\{u > 0\}$ of a Sobolev function $u \in H^1(\mathbb{R}^d)$

⁴under the additional constraint $\Omega \subset D$, where $D \subset \mathbb{R}^d$ is a bounded open set.

We study the Lipschitz continuity of the eigenfunctions u_k^ε on each Ω_ε and then pass to the limit to recover the Lipschitz continuity of u_k on Ω^* (see Theorem 5.3). The uniformity of the Lipschitz constants is assured, roughly speaking, by the optimality condition on the free boundary of Ω_ε , which, in the case of regular Ω_ε and simple eigenvalues, reads as

$$(1 - \varepsilon)|\nabla u_k^\varepsilon|^2 + \varepsilon|\nabla u_{k-1}^\varepsilon|^2 = c.$$

The main result of the paper is Theorem 5.7, which applies to shape supersolutions of functionals of the form

$$\Omega \mapsto F(\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega)) + |\Omega|,$$

where $F : \mathbb{R}^p \rightarrow \mathbb{R}$ is increasing and bi-Lipschitz in each variable. Precisely, if a set Ω^* satisfies

$$F(\lambda_{k_1}(\Omega^*), \dots, \lambda_{k_p}(\Omega^*)) + |\Omega^*| \leq F(\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega)) + |\Omega|,$$

for all measurable sets Ω containing Ω^* , then there exists a family of L^2 -orthonormal eigenfunctions u_{k_1}, \dots, u_{k_p} , corresponding respectively to $\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega)$, which are Lipschitz continuous on \mathbb{R}^d .

In some particular cases, as for example linear combinations of the form

$$F(\lambda_1(\Omega), \dots, \lambda_p(\Omega)) = \sum_{i=1}^p \alpha_i \lambda_i(\Omega),$$

with strictly positive α_i , for every $i = 1, \dots, p$, the minimizers are moreover proved to be open sets (see Corollary 6.3), since in this case there exists an open set $\Omega^{**} \subseteq \Omega^*$ which has the same eigenvalues of Ω^* up to order p . For this easier case, in two dimensions, it is also possible to give a more direct proof which does not rely on the Alt-Caffarelli regularity techniques (see [23]).

In [7], the analysis of shape subsolutions gave some qualitative information on the optimal sets, in particular their boundedness and finiteness of the perimeter. Nevertheless, it is known that a subsolution may not be equivalent to an open set. Continuity of the state functions in free boundary problems relies, in general, on outer perturbations. Consequently the study of supersolutions became a fundamental target, which is partially attained in this paper. In the case of subsolutions, the problem could be reduced to the analysis of a unique state function, precisely the torsion function, by controlling the variation of the k^{th} eigenvalue for an inner geometric domain perturbation with the variation of the torsional rigidity. As far as we know, an analogous approach for the analysis of shape supersolutions can not be performed since one can not control the variation of the torsional rigidity by the variation of the k^{th} eigenvalue.

This paper is organized as follows: in Section 2 we recall some tools about Sobolev-like spaces, capacity and γ -convergence; in Section 3 we deal with the Lipschitz regularity for quasi-minimizers of the Dirichlet energy and then, in Section 4, we apply these results to eigenfunctions of the Dirichlet Laplacian corresponding to a simple eigenvalue. Then in Section 5 we introduce the notion of shape supersolution and we prove our main results Theorem 5.3 and Theorem 5.7, concerning the Lipschitz regularity of the eigenfunctions associated to the general problem (1.1). At last, in Section 6, we show that for some functionals we are able to prove that optimal sets are open.

2 Preliminary results

In what follows, we will use the following notations and conventions:

- C_d denotes a constant depending only on the dimension d and if it is not specified it might change from line to line;
- ω_d denotes the volume of the unit ball in \mathbb{R}^d and thus $d\omega_d$ is the area of the unit sphere;
- \mathcal{H}^m denotes the m -dimensional Hausdorff measure in \mathbb{R}^d ;
- if the domain of integration is not specified, then it is assumed to be the whole space \mathbb{R}^d ;
- we denote the mean value of a function $u : \Omega \rightarrow \mathbb{R}$ with

$$\int_{\Omega} u \, dx := \frac{1}{|\Omega|} \int_{\Omega} u \, dx.$$

2.1 Sobolev spaces and spectral minimizers

Let $H \subset H^1(\mathbb{R}^d)$ be a closed linear subspace of $H^1(\mathbb{R}^d)$ such that the embedding $H \subset L^2(\mathbb{R}^d)$ is compact. We define the spectrum of the Laplace operator $-\Delta$ on H as

$$\lambda_k(H) = \min_{S_k} \max_{u \in S_k} \frac{\int |\nabla u|^2 \, dx}{\int u^2 \, dx},$$

where the minimum is over all k -dimensional subspaces S_k of H . In the case when $H = H_0^1(\Omega)$, where Ω is an open set of finite measure, we use the usual notation $\lambda_k(\Omega) := \lambda_k(H_0^1(\Omega))$ and thus the k^{th} eigenvalue of the Dirichlet Laplacian λ_k on Ω can be seen as a functional on the open sets $\Omega \subset \mathbb{R}^d$. In this paper we are interested in the regularity of the eigenfunctions on the sets Ω which are minimal with respect to exterior perturbations, i.e.

$$F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) \leq F(\lambda_1(\tilde{\Omega}), \dots, \lambda_k(\tilde{\Omega})) + c|\tilde{\Omega} \setminus \Omega|, \quad \forall \tilde{\Omega} \supset \Omega, \quad (2.1)$$

where F is a given function in \mathbb{R}^k , increasing in each variable. This is a property satisfied, for example, from the spectral minimizers, solution of the problem

$$\min \left\{ \lambda_k(\Omega) + |\Omega| : \Omega \subset \mathbb{R}^d \right\}. \quad (2.2)$$

Since, at the moment, the problem (2.2) is known to have solution only in the wider class of quasi-open sets (see [13, 7, 24]), we extend the definition of λ_k to a wider class of sets. Indeed, for every measurable $\Omega \subset \mathbb{R}^d$, we define the Sobolev space $H_0^1(\Omega)$ as

$$H_0^1(\Omega) = \left\{ u \in H^1(\mathbb{R}^d) : \text{cap}(\{u \neq 0\} \setminus \Omega) = 0 \right\}, \quad (2.3)$$

where for every $E \subset \mathbb{R}^d$ the capacity of E is defined as

$$\text{cap}(E) = \min \left\{ \|v\|_{H^1(\mathbb{R}^d)}^2 : v \in H^1(\mathbb{R}^d), v \geq 1 \text{ a.e. in a neighborhood of } E \right\}.$$

In the case when Ω is an open set the space defined in (2.3) coincides with the Sobolev space $H_0^1(\Omega)$ defined as the closure of $C_c^\infty(\Omega)$ with respect to the norm $\|\cdot\|_{H^1}$. We say that the set Ω is quasi-open, if it is a level set $\Omega = \{u > 0\}$ of a Sobolev function $u \in H^1(\mathbb{R}^d)$. In every measurable Ω , there is a largest quasi-open set $\omega \subset \Omega$ (defined up to a set of zero capacity), which is also such that $H_0^1(\omega) = H_0^1(\Omega)$.

In this paper we will deal mainly with the Sobolev-like spaces $\tilde{H}_0^1(\Omega)$, defined for every measurable $\Omega \subset \mathbb{R}^d$ as

$$\tilde{H}_0^1(\Omega) = \left\{ u \in H^1(\mathbb{R}^d) : |\{u \neq 0\} \setminus \Omega| = 0 \right\}. \quad (2.4)$$

The inclusion $H_0^1(\Omega) \subset \tilde{H}_0^1(\Omega)$ always holds, while the equality is achieved for open sets with Lipschitz boundary (see, for example, [18]) and it is not hard to construct open sets for which this equality is false (for example a ball minus one of its diameters). Thus we have $\lambda_k(\tilde{H}_0^1(\Omega)) \leq \lambda_k(H_0^1(\Omega))$. Moreover, for every measurable Ω there is a largest quasi-open set ω such that $\omega \subset \Omega$ a.e. and $H_0^1(\omega) = \tilde{H}_0^1(\omega) = \tilde{H}_0^1(\Omega)$. Thus, for every set Ω satisfying (2.1) there is a quasi-open set ω such that $\omega = \Omega$ a.e. and $H_0^1(\omega) = H_0^1(\Omega)$. Moreover, ω also satisfies (2.1) with the functional λ_k defined as

$$\lambda_k(\Omega) := \lambda_k(\tilde{H}_0^1(\Omega)), \text{ for every } \Omega \subset \mathbb{R}^d. \quad (2.5)$$

From now on, we will use (2.5) as a definition for λ_k . The main reason we use this definition is that, if the set of finite measure Ω satisfies (2.1), then for every $\varepsilon > 0$, Ω is the unique solution of

$$\min \left\{ F(\lambda_1(\tilde{\Omega}), \dots, \lambda_k(\tilde{\Omega})) + (c + \varepsilon)|\tilde{\Omega}| : \tilde{\Omega} \supset \Omega \right\}. \quad (2.6)$$

Indeed, one can easily check that if Ω_1 is a solution of (2.6), then $|\Omega_1 \Delta \Omega| = 0$ and so, $\tilde{H}_0^1(\Omega_1) = \tilde{H}_0^1(\Omega)$.

2.2 PDEs and eigenfunctions on measurable sets

Let $\Omega \subset \mathbb{R}^d$ be a set of finite Lebesgue measure and $f \in L^2(\Omega)$. We say that the function u satisfies the equation

$$-\Delta u = f, \quad u \in \tilde{H}_0^1(\Omega), \quad (2.7)$$

if, for every $v \in \tilde{H}_0^1(\Omega)$, we have

$$\langle \Delta u + f, v \rangle := - \int_{\mathbb{R}^d} \nabla u \cdot \nabla v \, dx + \int_{\mathbb{R}^d} f v \, dx = 0,$$

or analogously, if $u \in \tilde{H}_0^1(\Omega)$ is the minimizer of

$$\min \left\{ \frac{1}{2} \int_{\Omega} |\nabla v|^2 \, dx - \int_{\Omega} v f \, dx : v \in \tilde{H}_0^1(\Omega) \right\}.$$

If u is a solution of (2.7), then there is a signed Radon measure μ such that for every $v \in H^1(\mathbb{R}^d)$, we have

$$\langle \Delta u + f, v \rangle = \int_{\mathbb{R}^d} v \, d\mu.$$

In particular, Δu is a signed Radon measure on \mathbb{R}^d . Indeed, if $u \geq 0$, then the functional $\Delta u + f$ (defined on $H^1(\mathbb{R}^d)$) is positive. Applying the Riesz's Theorem we obtain the existence of the measure μ , which in this case is positive and finite on the compact sets (i.e. μ is a Radon measure). In the general case, we consider the functions $u^+ = \sup\{u, 0\}$ and $u^- = \sup\{-u, 0\}$. Each of the functionals $\Delta u^+ + fI_{\{u>0\}}$ and $\Delta u^- + fI_{\{u<0\}}$ is positive and so, there are measures μ_1 and μ_2 such that $\mu_1 = \Delta u^+ + fI_{\{u>0\}}$ and $\mu_2 = \Delta u^- + fI_{\{u<0\}}$. Thus, we have that the signed measure $\mu = \mu_1 - \mu_2$ is such that $\mu = \Delta u + f$. Moreover, we have that:

1. the support $\text{supp}(\mu)$ of μ is contained in the topological boundary $\partial\Omega$ of Ω ,

2. the measure μ is *capacitary*, i.e. for each set E of zero capacity, $\mu(E) = 0$.

If $u \in H^1(\mathbb{R}^d)$ is a solution of (2.7) with $f \in L^\infty(\Omega)$, then every point $x_0 \in \mathbb{R}^d$ is a Lebesgue point for u , i.e.

$$u(x_0) = \lim_{r \rightarrow 0} \int_{B_r(x_0)} u(x) dx.$$

Moreover, the following result was proved in [6].

Proposition 2.1. *Suppose that $\Omega \subset \mathbb{R}^d$ is a set of finite Lebesgue measure and $f \in L^\infty(\Omega)$. If $u \in \tilde{H}_0^1(\Omega)$ is a solution of (2.7), then for every $x \in \mathbb{R}^d$,*

$$u(x) = \lim_{r \rightarrow 0} \int_{\partial B_r(x)} u d\mathcal{H}^{d-1}, \quad (2.8)$$

and, for every $R > 0$,

$$\int_{\partial B_R(x)} u d\mathcal{H}^{d-1} - u(x) = \frac{1}{d\omega_d} \int_0^R r^{1-d} \Delta u(B_r(x)) dr. \quad (2.9)$$

Remark 2.2. *We note that the above propositions applies to the eigenfunctions of the Dirichlet Laplacian on Ω . Indeed, if u_k is a solution of*

$$-\Delta u_k = \lambda_k(\Omega) u_k, \quad u_k \in \tilde{H}_0^1(\Omega), \quad \int_{\Omega} u_k^2 dx = 1,$$

then we have the estimate (see [17, Example 2.1.8])

$$\|u_k\|_{L^\infty} \leq e^{1/8\pi} \lambda_k(\Omega)^{d/4}, \quad (2.10)$$

and so u_k satisfies the hypotheses of Proposition 2.1.

Most of the perturbation techniques, that we will use in order to prove the Lipschitz continuity if the state functions u on the optimal sets Ω , provide us with information on the mean values $\int_{B_r} u dx$ or $\int_{\partial B_r} u d\mathcal{H}^{d-1}$. In order to transfer this information to the gradient $|\nabla u|$, we will need the following classical result.

Remark 2.3 (Gradient estimate). *Let $u \in H^1(B_r)$ is such that $-\Delta u = f$ in B_r and $f \in L^\infty(B_r)$. Then we have*

$$\|\nabla u\|_{L^\infty(B_{r/2})} \leq C_d \|f\|_{L^\infty(B_r)} + \frac{2d}{r} \|u\|_{L^\infty(B_r)}. \quad (2.11)$$

Note that, one can replace in (2.11) $\|u\|_{L^\infty(B_r)}$ with the integral of $|u|$ on the boundary ∂B_r . In fact, we have the following estimate:

$$\|u\|_{L^\infty(B_{2r/3})} \leq \frac{r^2}{2d} \|f\|_{L^\infty(B_r)} + C_d \int_{\partial B_r} |u| d\mathcal{H}^{d-1}. \quad (2.12)$$

Since, $\Delta u^+ + f I_{\{u>0\}} \geq 0$ and $\Delta u^- - f I_{\{u<0\}} \geq 0$ in B_r , we have that $\Delta|u| + \|f\|_{L^\infty} \geq 0$ in B_r . Let u_h be the harmonic function in B_r with boundary values $u_h = |u|$ on ∂B_r . Since $|u|$ is non-negative, the same holds for u_h and applying the Poisson's formula for the disk we have that

$$\|u_h\|_{L^\infty(B_{2r/3})} \leq C_d \int_{\partial B_r} |u| d\mathcal{H}^{d-1}. \quad (2.13)$$

Moreover, by the maximum principle, we have that for any $x \in B_r$

$$||u| - u_h|(x) \leq \frac{r^2 - |x|^2}{2d} \|f\|_{L^\infty(B_r)}. \quad (2.14)$$

Putting together the two estimates, we have:

$$\begin{aligned} \|u\|_{L^\infty(B_{2r/3})} &\leq \frac{r^2}{2d} \|f\|_{L^\infty(B_r)} + \|u_h\|_{L^\infty(B_{2r/3})} \\ &\leq \frac{r^2}{2d} \|f\|_{L^\infty(B_r)} + C_d \int_{\partial B_r} |u| d\mathcal{H}^{d-1}. \end{aligned}$$

2.3 The γ and weak- γ convergences

In the proof of our main result (Theorem 5.3) we will use a variational convergence defined on the measurable sets of finite Lebesgue measure. Indeed, for every $\Omega \subset \mathbb{R}^d$ with $|\Omega| < +\infty$, we will denote with w_Ω the solution of

$$-\Delta w_\Omega = 1, \quad w_\Omega \in \tilde{H}_0^1(\Omega).$$

We note that a measurable set $\Omega \subset \mathbb{R}^d$ is precisely determined, as a domain of the Sobolev space $\tilde{H}_0^1(\Omega)$, by the *energy function* w_Ω . In fact, we have the equality

$$\tilde{H}_0^1(\Omega) = \tilde{H}_0^1(\{w_\Omega > 0\}).$$

If the measurable set Ω is such that $|\Omega \Delta \{w_\Omega > 0\}| = 0$, then we can choose its representative in the family of measurable set to be precisely the set $\{w_\Omega > 0\}$.

Definition 2.4. We say that the sequence of sets of finite measure Ω_n

- γ -converges to the set Ω , if the sequence w_{Ω_n} converges strongly in $L^2(\mathbb{R}^d)$ to the function w_Ω ;
- weak- γ -converges to the set Ω , if the sequence w_{Ω_n} converges strongly in $L^2(\mathbb{R}^d)$ to the function $w \in H^1(\mathbb{R}^d)$ and $\Omega = \{w > 0\}$.

We note that in the case of a weak- γ -converging sequence $\Omega_n \rightarrow \Omega$, there is a comparison principle between the limit function $w = L^2 - \lim_{n \rightarrow \infty} w_{\Omega_n}$ and the energy function w_Ω . Indeed, we have the inequality $w \leq w_\Omega$, which follows by the variational characterization of w , through the so called *capacitary measures*, or it can also be proved directly by comparing the functions w_{Ω_n} to w_Ω (see [10]). Using only this weak maximum principle and the definitions above, one may deduce the following properties of the γ and the weak- γ convergences (for more details we refer the reader to the papers [11, 13] and the books [8, 20]).

Remark 2.5 (γ and weak- γ -convergences). If Ω_n γ -converges to Ω , then it also weak- γ -converges to Ω . Under the additional assumption $\Omega \subset \Omega_n$, for every $n \in \mathbb{N}$, we have that if Ω_n weak- γ -converges to Ω , then Ω_n γ -converges to Ω .

Remark 2.6 (measure and weak- γ -convergences). If Ω_n converges to Ω in $L^1(\mathbb{R}^d)$, i.e. $|\Omega_n \Delta \Omega| \rightarrow 0$, then up to a subsequence Ω_n weak- γ -converges to Ω . On the other hand, if Ω_n weak- γ -converges to Ω , then we have the following semi-continuity of the Lebesgue measure:

$$|\Omega| \leq \liminf_{n \rightarrow \infty} |\Omega_n|.$$

Remark 2.7 (γ and Mosco convergences). (a) Suppose that Ω_n weak- γ -converges to Ω . Then, if the sequence $u_n \in \tilde{H}_0^1(\Omega_n)$ converges in $L^2(\mathbb{R}^d)$ to $u \in H^1(\mathbb{R}^d)$, we have that $u \in \tilde{H}_0^1(\Omega)$. In particular, we obtain the semi-continuity of λ_k , with respect to the weak- γ -convergence:

$$\lambda_k(\Omega) \leq \liminf_{n \rightarrow \infty} \lambda_k(\Omega_n).$$

(b) Suppose that Ω_n γ -converges to Ω . Then, for every $u \in \tilde{H}_0^1(\Omega)$, there is a sequence $u_n \in \tilde{H}_0^1(\Omega_n)$ converging to u strongly in $H^1(\mathbb{R}^d)$. As a consequence, we have the continuity of λ_k with respect to the γ -convergence:

$$\lambda_k(\Omega) = \lim_{n \rightarrow \infty} \lambda_k(\Omega_n).$$

3 Lipschitz continuity of energy quasi-minimizers

In this section we study the properties of the local quasi-minimizers for the Dirichlet integral. More precisely, let $f \in L^2(\mathbb{R}^d)$ and let $u \in H^1(\mathbb{R}^d)$ satisfies

$$-\Delta u = f, \quad u \in \tilde{H}_0^1(\{u \neq 0\}). \quad (3.1)$$

Definition 3.1. We say that u is a quasi-minimizer for the functional

$$J_f(u) = \frac{1}{2} \int_{\mathbb{R}^d} |\nabla u|^2 dx - \int_{\mathbb{R}^d} u f dx, \quad (3.2)$$

if there is a positive constant C such that for every $r > 0$ we have

$$J_f(u) \leq J_f(v) + Cr^d, \quad \forall v \in \mathcal{A}_r(u), \quad (3.3)$$

where the admissible set $\mathcal{A}_r(u)$ is defined as

$$\mathcal{A}_r(u) := \left\{ v \in H^1(\mathbb{R}^d) : \exists x_0 \in \mathbb{R}^d \text{ such that } v - u \in H_0^1(B_r(x_0)) \right\}.$$

Definition 3.2. We say that u is a local quasi-minimizer, if there are positive constants α and r_0 such that for every $0 < r \leq r_0$ we have

$$J_f(u) \leq J_f(v) + Cr^d, \quad \forall v \in \mathcal{A}_{r,\alpha}(u), \quad (3.4)$$

where the admissible set $\mathcal{A}_{r,\alpha}(u)$ is defined as

$$\mathcal{A}_{r,\alpha}(u) := \left\{ v \in H^1(\mathbb{R}^d) : \exists x_0 \in \mathbb{R}^d \text{ s.t. } v - u \in H_0^1(B_r(x_0)), \int |\nabla(u - v)|^2 dx \leq \alpha \right\}.$$

Remark 3.3. The local quasi-minimality condition is equivalent to suppose that for every ball $B_r(x_0)$, of radius smaller than r_0 , and every $\varphi \in H_0^1(B_r(x_0))$, such that $\int |\nabla \varphi|^2 dx \leq \alpha$, we have

$$|\langle \Delta u + f, \varphi \rangle| \leq \frac{1}{2} \int_{B_r(x_0)} |\nabla \varphi|^2 dx + Cr^d. \quad (3.5)$$

Moreover, if for some constant $C > 0$ u satisfies

$$|\langle \Delta u + f, \varphi \rangle| \leq C \left(\int_{B_r(x_0)} |\nabla \varphi|^2 dx + r^d \right), \quad (3.6)$$

for r and φ , as above, then setting $\tilde{\varphi} = (2C)^{-1}\varphi$, we have that u satisfies (3.5) and so, is a quasi-minimizer.

Remark 3.4. Let $\psi \in H_0^1(B_r(x_0))$. Testing (3.5) with $\varphi := r^{d/2} \|\nabla\psi\|_{L^2}^{-1} \psi$, we obtain that the quasi-minimality of u gives

$$|\langle \Delta u + f, \psi \rangle| \leq Cr^{d/2} \left(\int_{B_r(x_0)} |\nabla\psi|^2 dx \right)^{1/2}. \quad (3.7)$$

Moreover, by the mean geometric-mean quadratic inequality, we have that condition (3.7) is equivalent to the quasi-minimality of u .

Remark 3.5. If $f \in L^\infty(\mathbb{R}^d)$ and the support Ω is of finite Lebesgue measure, then the quasi-minimality of u with respect to J is equivalent to the quasi-minimality of u with respect to the Dirichlet integral

$$J_0(u) = \int_{\mathbb{R}^d} |\nabla u|^2 dx.$$

In what follows we prove a Theorem concerning the Lipschitz continuity of the local quasi-minimizers. This result is a consequence of the techniques introduced by Briançon, Hayouni and Pierre [6].

Theorem 3.6. Let $\Omega \subset \mathbb{R}^d$ be a measurable set of finite measure, $f \in L^\infty(\Omega)$ and the function $u \in H^1(\mathbb{R}^d)$ be such that

(a) u is a solution of the following equation on Ω

$$-\Delta u = f, \quad u \in \tilde{H}_0^1(\Omega);$$

(b) u is a local quasi-minimizer for the functional J_f , i.e. there are constants $r_0 \leq 1$ and C_b such that for every $x \in \mathbb{R}^d$, every $0 < r \leq r_0$ and every $\varphi \in H_0^1(B_r(x))$ we have

$$|\langle \Delta u + f, \varphi \rangle| \leq C_b \|\nabla\varphi\|_{L^2} |B_r|^{1/2}. \quad (3.8)$$

Then:

(1) u is Lipschitz continuous on \mathbb{R}^d and the Lipschitz constant depends on d , $\|f\|_\infty$, $|\Omega|$, C_b and r_0 .

(2) the distribution $\Delta|u|$ is a Borel measure satisfying

$$|\Delta|u|| (B_r(x)) \leq Cr^{d-1}, \quad (3.9)$$

for every $x \in \mathbb{R}^d$ such that $u(x) = 0$, where the constant C depends on d , $\|f\|_\infty$, $|\Omega|$ and C_b (but not on r_0).

A precise account on the Lipschitz constant of u from Theorem 3.6 is

$$\|u\|_{C^{0,1}} \leq C_d \left(1 + |\Omega|^{\frac{d+4}{2d}} + C_b + \frac{|\Omega|^{\frac{2}{d}}}{r_0} \right) \|f\|_\infty.$$

We notice that condition (b) is also necessary for the Lipschitz continuity of u . In fact, it expresses in a weak form the boundedness of the gradient $|\nabla u|$ on the boundary $\partial\Omega$.

The proof of this theorem is implicitly contained in [6, Theorem 3.1]. For the sake of completeness, we reproduce it in the Appendix.

Theorem 3.7. Under the hypotheses of Theorem 3.6, assume that u is a normalized eigenfunction (i.e. there exists $\lambda > 0$ such that $f = \lambda u$ and $\int u^2 dx = 1$) satisfying condition (a) and (b). Then, the Lipschitz constant is independent of r_0 .

Proof. We first notice that by (2.10) we have $\|f\|_\infty = \lambda\|u\|_\infty \leq 2\lambda^{\frac{d+4}{4}}$. By Theorem 3.6, applied to u and $f := \lambda u$, we have that u is Lipschitz continuous. We shall prove that the Lipschitz constant is independent on r_0 . We set $\tilde{\Omega} := \{u \neq 0\}$ and we note that $\tilde{\Omega}$ is an open set. Let x be such that $d(x, \tilde{\Omega}^c) < \min\{r_0/3, 1\}$ and let $y \in \partial\tilde{\Omega}$ such that $R_x := d(x, \tilde{\Omega}^c) = |x - y|$. Following Remark 2.3

$$\begin{aligned} |\nabla u(x)| &\leq C_d \lambda \|u\|_{L^\infty} + \frac{2d}{R_x} \|u\|_{L^\infty(B_{R_x}(x))} \\ &\leq C_d \lambda \|u\|_{L^\infty} + \frac{2d}{R_x} \|u\|_{L^\infty(B_{2R_x}(y))} \\ &\leq (C_d + R_x) \lambda \|u\|_{L^\infty} + \frac{C_d}{R_x} \int_{\partial B_{3R_x}(y)} |u| d\mathcal{H}^{d-1}. \end{aligned} \quad (3.10)$$

The last inequality comes from the estimate on $B_{2R_x}(y)$ of the function

$$|u(\cdot)| - \frac{(3R_x)^2 - |\cdot|^2}{2d} \lambda \|u\|_\infty,$$

which is sub-harmonic on the ball $B_{3R_x}(y)$ (see Remark 2.3). Hence

$$\begin{aligned} |\nabla u(x)| &\leq (C_d + R_x) \lambda \|u\|_{L^\infty} + \frac{C_d}{R_x} \int_0^{3R_x} s^{1-d} |\Delta |u|| (B_s(y)) ds \\ &\leq (C_d + R_x) \lambda \|u\|_{L^\infty} + 3C_d C, \end{aligned} \quad (3.11)$$

where C is the constant from (3.9).

Consider the function $P \in C^\infty(\tilde{\Omega})$ defined as

$$P := |\nabla u|^2 + \lambda u^2 - 2\lambda^2 \|u\|_\infty^2 w_{\tilde{\Omega}}, \quad (3.12)$$

where $w_{\tilde{\Omega}}$ is the solution of the equation

$$-\Delta w_{\tilde{\Omega}} = 1, \quad w_{\tilde{\Omega}} \in H_0^1(\tilde{\Omega}).$$

A direct computation gives that P is sub-harmonic on the open set $\tilde{\Omega}$, i.e.

$$\Delta P = (2[\text{Hess}(u)]^2 - 2\lambda|\nabla u|^2) + (2\lambda|\nabla u|^2 - 2\lambda^2 u^2) + 2\lambda^2 \|u\|_\infty^2 \geq 0. \quad (3.13)$$

Thus, by the maximum principle we get

$$\sup \{P(x) : x \in \tilde{\Omega}\} \leq \sup \{P(x) : x \in \tilde{\Omega}, \text{dist}(x, \partial\tilde{\Omega}) < r_0/3\},$$

and so, using the boundary estimate (3.11), we obtain

$$\|\nabla u\|_\infty^2 \leq 2\lambda^2 \|u\|_\infty^2 \|w_{\tilde{\Omega}}\|_\infty + 2\lambda \|u\|_\infty^2 + ((C_d + 1)\lambda \|u\|_{L^\infty} + 3C_d C)^2. \quad (3.14)$$

Now the conclusion follows by (2.10) and the classical bound $\|w_{\tilde{\Omega}}\|_\infty \leq C_d |\tilde{\Omega}|^{2/d}$ (see, for example, [26, Theorem 1]).

□

Remark 3.8. Notice that the Lipschitz norm of u satisfying the hypotheses of Theorem 3.7, depends ultimately on d , $|\Omega|$ and λ .

4 Shape quasi-minimizers for Dirichlet eigenvalues

In this section we discuss the regularity of the eigenfunctions on sets which are minimal with respect to a given (spectral) shape functional. In what follows we denote with \mathcal{A} the family of subset of \mathbb{R}^d with finite Lebesgue measure endowed with the equivalence relation $\Omega \sim \tilde{\Omega}$, whenever $|\Omega \Delta \tilde{\Omega}| = 0$.

Definition 4.1. *We say that the measurable set $\Omega \in \mathcal{A}$ is a shape quasi-minimizer for the functional $\mathcal{F} : \mathcal{A} \rightarrow \mathbb{R}$, if there exist constants $C > 0$ and $r_0 > 0$ such that every $0 < r \leq r_0$ we have*

$$\mathcal{F}(\Omega) \leq \mathcal{F}(\tilde{\Omega}) + C|B_r|, \quad \forall \tilde{\Omega} \in \mathcal{A}_r(\Omega),$$

where the admissible set of perturbations $\mathcal{A}_r(\Omega)$ is given by

$$\mathcal{A}_r(\Omega) = \left\{ \tilde{\Omega} \in \mathcal{A} : \exists x \in \mathbb{R}^d \text{ such that } \Omega \Delta \tilde{\Omega} \subseteq B_r(x) \right\}.$$

Remark 4.2. *If the functional \mathcal{F} is non-increasing with respect to inclusions, then Ω is a shape quasi-minimizer, if and only if,*

$$\mathcal{F}(\Omega) \leq \mathcal{F}(\Omega \cup B_r(x)) + C|B_r|.$$

We expect that the property of shape quasi-minimality contains some information on the regularity of Ω . In fact, for some shape functionals \mathcal{F} one can easily deduce from the shape quasi-minimality of Ω the quasi-minimality of the state functions on Ω . For example, suppose that Ω is a shape quasi-minimizer for the Dirichlet Energy

$$E(\Omega) := \min \left\{ J_1(u) : u \in \tilde{H}_0^1(\Omega) \right\}.$$

Then, for $r > 0$ small enough and $\tilde{\Omega} \Delta \Omega \subset B_r(x)$, we have

$$J_1(w_\Omega) = E(\Omega) \leq E(\tilde{\Omega}) + C|B_r| \leq J_1(w_\Omega + \varphi) + C|B_r|,$$

where $w_\Omega \in \tilde{H}_0^1(\Omega)$ is the energy function on Ω and φ is any function from $H_0^1(B_r)$. Thus the function w_Ω is a quasi-minimizer for the functional J_1 in sense of Definition 3.2 and so, by Theorem 3.6, we can conclude that the energy function w_Ω is Lipschitz continuous on \mathbb{R}^d .

The case $\mathcal{F} = \lambda_k$ is more involved, since the k^{th} eigenvalue is not defined through a single state function, but is variationally characterized by a min-max procedure involving an entire linear subspace of $\tilde{H}_0^1(\Omega)$. In order to transfer the minimality information from Ω to its eigenfunctions u_k , we need an estimate on the variation of λ_k , with respect to external perturbation, in terms of the variation of the energy of u_k .

In Lemma 4.3 below, we assume that Ω is a generic set of finite measure and $l \geq 1$ is such that

$$\lambda_k(\Omega) = \dots = \lambda_{k-l+1}(\Omega) > \lambda_{k-l}(\Omega). \quad (4.1)$$

We also choose u_{k-l+1}, \dots, u_k to be l normalized orthogonal eigenfunctions corresponding to k^{th} eigenvalue $\lambda_k(\Omega)$ of the Dirichlet Laplacian on Ω .

The following notation is used: given a vector $\alpha = (\alpha_{k-l+1}, \dots, \alpha_k) \in \mathbb{R}^l$, we denote with \mathbf{u}_α the corresponding linear combination

$$\mathbf{u}_\alpha = \alpha_{k-l+1}u_{k-l+1} + \dots + \alpha_k u_k. \quad (4.2)$$

Lemma 4.3. *Let $\Omega \subset \mathbb{R}^d$ be a set of finite measure and $l \geq 1$ is such that (4.1) holds. Then there is a constant $r_0 > 0$ such that for every $x \in \mathbb{R}^d$, every $0 < r < r_0$ and every l -uple of functions $v_{k-l+1}, \dots, v_k \in H_0^1(B_r(x))$ with $\int |\nabla v_j|^2 \leq 1$, for $j = k-l+1, \dots, k$, there is a unit vector $\alpha \in \mathbb{R}^l$ such that*

$$\lambda_k(\Omega \cup B_r(x)) \leq \frac{\int |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx + (\lambda_{k-l}(\Omega) + 1) \int |\nabla \mathbf{v}_\alpha|^2 dx}{\int |\mathbf{u}_\alpha + \mathbf{v}_\alpha|^2 dx - \frac{1}{2} \int |\nabla \mathbf{v}_\alpha|^2 dx}, \quad (4.3)$$

where $\mathbf{u}_\alpha, \mathbf{v}_\alpha$ are defined using notation (4.2).

The constant r_0 depends on Ω . In particular, if the gap $\lambda_{k-l+1}(\Omega) - \lambda_{k-l}(\Omega)$ vanishes, r_0 vanishes as well.

Proof. Without loss of generality, we can suppose $x = 0$. By the definition of the k^{th} eigenvalue, we know that

$$\lambda_k(\Omega \cup B_r) \leq \max \left\{ \frac{\int |\nabla u|^2 dx}{\int u^2 dx} : u \in \text{span} \langle u_1, \dots, u_{k-l}, u_{k-l+1} + v_{k-l+1}, \dots, u_k + v_k \rangle \right\}.$$

The maximum is attained for a linear combination

$$\alpha_1 u_1 + \dots + \alpha_{k-l} u_{k-l} + \alpha_{k-l+1} (u_{k-l+1} + v_{k-l+1}) + \dots + \alpha_k (u_k + v_k).$$

Note that if $\lambda_{k-l}(\Omega) < \lambda_k(\Omega \cup B_r)$, then the vector

$$\alpha = (\alpha_{k-l+1}, \dots, \alpha_k) \in \mathbb{R}^l,$$

is non zero, and moreover can be chosen to be unitary. The inequality $\lambda_{k-l}(\Omega) < \lambda_k(\Omega \cup B_r(x))$, is true for every x and every $r < r_0$ provided r_0 is small enough. This can be proved for instance by contradiction, since for every $x_n \in \mathbb{R}^d$ and for every $r_n \rightarrow 0$, we have that $\Omega \cup B_{r_n}(x_n)$ γ -converges to Ω .

For simplicity, we denote $\lambda_j = \lambda_j(\Omega)$, for every j .

Using the notation (4.2), for r_0 small enough, we have

$$\begin{aligned} \frac{\int |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx}{\int |\mathbf{u}_\alpha + \mathbf{v}_\alpha|^2 dx} &= \frac{\lambda_k + 2 \int \nabla \mathbf{u}_\alpha \cdot \nabla \mathbf{v}_\alpha dx + \int |\nabla \mathbf{v}_\alpha|^2 dx}{1 + 2 \int \mathbf{u}_\alpha \mathbf{v}_\alpha dx + \int \mathbf{v}_\alpha^2 dx} \\ &\geq \frac{\lambda_k - 2 \left(\int_{B_r} |\nabla \mathbf{u}_\alpha|^2 dx \right)^{1/2} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}}{1 + 2 \left(\int_{B_r} \mathbf{u}_\alpha^2 dx \right)^{1/2} \left(\int_{B_r} \mathbf{v}_\alpha^2 dx \right)^{1/2} + \int \mathbf{v}_\alpha^2 dx} \\ &\geq \frac{\lambda_k - 2 \left(\int_{B_{r_0}} |\nabla \mathbf{u}_\alpha|^2 dx \right)^{1/2} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}}{1 + 2 \left(\int_{B_r} \mathbf{v}_\alpha^2 dx \right)^{1/2} + \int_{B_r} \mathbf{v}_\alpha^2 dx} \\ &\geq \frac{\lambda_k - 2 \left(\int_{B_{r_0}} |\nabla \mathbf{u}_\alpha|^2 dx \right)^{1/2} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}}{1 + 2C_d |B_{r_0}|^{1/d} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2} + |C_d B_{r_0}|^{2/d} \int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx} \\ &\geq \frac{\lambda_{k-l} + \lambda_k}{2}. \end{aligned} \quad (4.4)$$

If all α_i for $i = 1, \dots, k-l$ are zero, then the assertion of the theorem is trivially true. Otherwise, we define

$$u = \frac{1}{\sqrt{\alpha_1^2 + \dots + \alpha_{k-l}^2}} (\alpha_1 u_1 + \dots + \alpha_{k-l} u_{k-l}).$$

So $\int u^2 = 1$ and $\int |\nabla u|^2 \leq \lambda_{k-l}$.
Consequently,

$$\lambda_k(\Omega \cup B_r) \leq \max \left\{ \frac{\int |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha + tu)|^2 dx}{\int |\mathbf{u}_\alpha + \mathbf{v}_\alpha + tu|^2 dx} : t \in \mathbb{R} \right\}.$$

We have

$$\begin{aligned} \frac{\int |\nabla(tu + \mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx}{\int (tu + \mathbf{u}_\alpha + \mathbf{v}_\alpha)^2 dx} &\leq \frac{t^2 \lambda_{k-l}(\Omega) + 2t \int \nabla u \cdot \nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha) dx + \int |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx}{t^2 + 2t \int u(\mathbf{u}_\alpha + \mathbf{v}_\alpha) dx + \int |\mathbf{u}_\alpha + \mathbf{v}_\alpha|^2 dx} \\ &= \frac{t^2 \lambda_{k-l}(\Omega) + 2t \int \nabla u \cdot \nabla \mathbf{u}_\alpha dx + 2t \int_{B_r} \nabla u \cdot \nabla \mathbf{v}_\alpha dx + \int_{\mathbb{R}^d} |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx}{t^2 + 2t \int u \mathbf{u}_\alpha dx + 2t \int_{B_r} u \mathbf{v}_\alpha dx + \int_{\mathbb{R}^d} |\mathbf{u}_\alpha + \mathbf{v}_\alpha|^2 dx} \\ &= \frac{t^2 \lambda_{k-l}(\Omega) + 2t \int_{B_r} \nabla u \cdot \nabla \mathbf{v}_\alpha dx + \int_{\mathbb{R}^d} |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx}{t^2 + 2t \int_{B_r} u \mathbf{v}_\alpha dx + \int |\mathbf{u}_\alpha + \mathbf{v}_\alpha|^2 dx} := F(t). \end{aligned} \quad (4.5)$$

For sake of simplicity we pose:

$$\begin{aligned} a &= \int_{B_r} \nabla u \cdot \nabla \mathbf{v}_\alpha dx, & b &= \int_{B_r} u \mathbf{v}_\alpha dx, \\ A &= \int_{\mathbb{R}^d} |\nabla(\mathbf{u}_\alpha + \mathbf{v}_\alpha)|^2 dx, & B &= \int_{\mathbb{R}^d} |\mathbf{u}_\alpha + \mathbf{v}_\alpha|^2 dx. \end{aligned} \quad (4.6)$$

Note that we can make a and b arbitrarily small, by choosing r_0 small enough. In fact, we have the following estimates:

$$|a| \leq \left(\int_{B_r} |\nabla u|^2 dx \right)^{1/2} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2} \leq \left(\int_{B_{r_0}} |\nabla u|^2 dx \right)^{1/2} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}, \quad (4.7)$$

$$|b| \leq \left(\int_{B_r} u^2 dx \right)^{1/2} \left(\int_{B_r} \mathbf{v}_\alpha^2 dx \right)^{1/2} \leq C_d r_0 \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}. \quad (4.8)$$

Moreover, we can suppose that

$$\lambda_k/2 \leq A \leq 2\lambda_k + 1, \quad 1/2 \leq B \leq 2.$$

By (4.4) and the fact that $\lim_{t \rightarrow \pm\infty} F(t) = \lambda_{k-l} < \frac{\lambda_{k-l} + \lambda_k}{2} \leq F(0)$, we have that the maximum of F is attained in \mathbb{R} . Computing the derivative, the zeros t of F' satisfy

$$(\lambda_{k-l}t + a)(t^2 + 2bt + B) - (t + b)(\lambda_{k-l}t^2 + 2at + A) = 0,$$

or, after simplification,

$$t^2(\lambda_{k-l}b - a) + t(\lambda_{k-l}B - A) + (aB - bA) = 0.$$

Thus, we have that $\|F\|_\infty = \max\{F(t_1), F(t_2)\}$, where

$$\begin{aligned} t_{1,2} &= \frac{A - \lambda_{k-l}B \pm \sqrt{(A - \lambda_{k-l}B)^2 - 4(\lambda_{k-l}b - a)(aB - bA)}}{2(\lambda_{k-l}b - a)} \\ &= \frac{A - \lambda_{k-l}B}{2(\lambda_{k-l}b - a)} \left(1 \pm \sqrt{1 - \frac{4(\lambda_{k-l}b - a)(aB - bA)}{(A - \lambda_{k-l}B)^2}} \right) \end{aligned} \quad (4.9)$$

We choose r_0 small enough, in order to have

$$\left| \frac{4(\lambda_{k-l}b - a)(aB - bA)}{(A - \lambda_{k-l}B)^2} \right| < \frac{1}{2}.$$

Then, since the function $x \mapsto \sqrt{1-x}$ is bounded and 1-Lipschitz on the interval $(-\frac{1}{2}, \frac{1}{2})$, we have the following estimate

$$\begin{aligned} |t_1| &= \left| \frac{A - \lambda_{k-l}B}{2(\lambda_{k-l}b - a)} \left(1 - \sqrt{1 - \frac{4(\lambda_{k-l}b - a)(aB - bA)}{(A - \lambda_{k-l}B)^2}} \right) \right| \\ &\leq \left| \frac{A - \lambda_{k-l}B}{2(\lambda_{k-l}b - a)} \right| \cdot \left| \frac{4(\lambda_{k-l}b - a)(aB - bA)}{(A - \lambda_{k-l}B)^2} \right| \\ &\leq 2 \left| \frac{aB - bA}{A - \lambda_{k-l}B} \right| \leq 2 \frac{|a|B + |b|A}{A - \lambda_{k-l}B} \leq 4 \frac{|a| + \lambda_k|b|}{A - \lambda_{k-l}B} \\ &\leq 16 \frac{|a| + \lambda_k|b|}{\lambda_k - \lambda_{k-l}} \leq \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}. \end{aligned} \quad (4.10)$$

The last inequality is obtained using (4.7) and (4.8), for r_0 small enough. On the other hand, for t_2 , we have

$$\frac{1}{2} \left| \frac{A - \lambda_{k-l}B}{\lambda_{k-l}b - a} \right| \leq |t_2| \leq 2 \left| \frac{A - \lambda_{k-l}B}{\lambda_{k-l}b - a} \right|. \quad (4.11)$$

Note that if we choose r_0 such that $|t_1| < |t_2|$, then the maximum cannot be attained in t_2 . In fact, $(\lambda_{k-l}b - a)t_2 > 0$ and so, in t_2 , the derivative F' changes sign from negative to positive, if $t_2 > 0$ and from negative to positive, if $t_2 < 0$, which proves that the maximum is attained in t_1 . Choosing r_0 such that

$$|a| \leq \frac{1}{2} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}, \quad |b| \leq \frac{1}{4} \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2},$$

we have

$$\begin{aligned} F(t_1) &\leq \frac{\lambda_{k-l}t_1^2 + 2at_1 + A}{t_1^2 + 2bt_1 + B} \leq \frac{\lambda_{k-l}t_1^2 + |2at_1| + A}{t_1^2 - |2bt_1| + B} \\ &\leq \frac{\lambda_{k-l} \int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx + 2|a| \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2} + A}{B - 2|b| \left(\int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx \right)^{1/2}} \\ &\leq \frac{A + (\lambda_{k-l} + 1) \int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx}{B - \frac{1}{2} \int_{B_r} |\nabla \mathbf{v}_\alpha|^2 dx}, \end{aligned} \quad (4.12)$$

and so, the conclusion. \square

Remark 4.4. *The preceding Lemma 4.3 points out the main difficulty in the study of the regularity of spectral minimizers. Indeed, let Ω^* be a solution of a spectral optimization problem of the form (1.1) involving λ_k and such that (4.1) holds for some $l > 1$. Then every perturbation $\tilde{u}_k = u_k + v$ of the eigenfunction $u_k \in \tilde{H}_0^1(\Omega^*)$ gives information on a linear combination \mathbf{u}_α of eigenfunctions u_k, \dots, u_{k-l+1} , instead on the function u_k . Recovering some information on u_k from an estimate on the linear combination is a difficult task since the combination itself depends on the perturbation v .*

Remark 4.5. *In case $\lambda_k(\Omega) > \lambda_{k-1}(\Omega)$, the result of the lemma above, states as*

$$\lambda_k(\Omega \cup B_r(x)) \leq \frac{\int |\nabla(u_k + v)|^2 dx + (\lambda_{k-1}(\Omega) + 1) \int |\nabla v|^2 dx}{\int |u_k + v|^2 dx - \frac{1}{2} \int |\nabla v|^2 dx}, \quad (4.13)$$

for every $r < r_0$ and every $v \in H_0^1(B_r(x))$ such that $\int |\nabla v|^2 dx \leq 1$.

Lemma 4.6. *Let $\Omega \subset \mathbb{R}^d$ be a shape quasi-minimizer for λ_k such that $\lambda_k(\Omega) > \lambda_{k-1}(\Omega)$. Then every eigenfunction $u_k \in \tilde{H}_0^1(\Omega)$, normalized in L^2 and corresponding to the eigenvalue $\lambda_k(\Omega)$, is Lipschitz continuous on \mathbb{R}^d .*

Proof. Let u_k be a normalized eigenfunction corresponding to λ_k . By the shape quasi-minimality of Ω , we have

$$\lambda_k(\Omega) \leq \lambda_k(\Omega \cup B_r(x)) + C|B_r|. \quad (4.14)$$

Applying the estimate (4.13) for $v \in H_0^1(B_r)$, we obtain

$$|\langle \Delta u_k + \lambda_k(\Omega)u_k, v \rangle| \leq C|B_r| + (\lambda_k(\Omega) + 1) \int |\nabla v|^2 dx, \quad (4.15)$$

and so, the function u_k is a quasi-minimizer for the functional

$$u \mapsto \frac{1}{2} \int_{\mathbb{R}^d} |\nabla u|^2 dx - \int_{\mathbb{R}^d} \lambda_k(\Omega)u_k u dx.$$

Since u_k is bounded by (2.10), the claim follows by Theorem 3.7. \square

5 Shape supersolutions of spectral functionals

Definition 5.1. *We say that the set $\Omega \subset \mathbb{R}^d$ is a shape supersolution for the functional $\mathcal{F} : \mathcal{A} \rightarrow \mathbb{R}$, defined on the class of Lebesgue measurable sets \mathcal{A} , if Ω satisfies*

$$\mathcal{F}(\Omega) \leq \mathcal{F}(\tilde{\Omega}), \quad \forall \tilde{\Omega} \supset \Omega.$$

Remark 5.2. \bullet *If Ω^* is a shape supersolution for $\mathcal{F} + \Lambda|\cdot|$, for some $\Lambda > 0$, then for every $\Lambda' > \Lambda$ the set Ω^* is the unique solution of*

$$\min \left\{ \mathcal{F}(\Omega) + \Lambda'|\Omega| : \Omega \text{ Lebesgue measurable, } \Omega \supset \Omega^* \right\}.$$

- \bullet *If the functional \mathcal{F} is non-increasing with respect to the inclusion, we have, by Remark 4.2, that every shape supersolution Ω of $\mathcal{F} + \Lambda|\cdot|$, where $\Lambda > 0$, is also a shape quasi-minimizer.*

In Lemma 4.6 we showed that the k^{th} eigenfunctions of the the shape quasi-minimizers for λ_k are Lipschitz continuous under the assumption $\lambda_k(\Omega) > \lambda_{k-1}(\Omega)$. In the next Theorem, we show that for shape supersolutions of $\lambda_k + \Lambda|\cdot|$ the later assumption can be dropped.

Theorem 5.3. *Let $\Omega^* \subset \mathbb{R}^d$ be a bounded shape supersolution for the functional $\lambda_k + \Lambda|\cdot|$, for some $\Lambda > 0$. Then there is an eigenfunction $u_k \in \widetilde{H}_0^1(\Omega^*)$, normalized in L^2 and corresponding to the eigenvalue $\lambda_k(\Omega^*)$, which is Lipschitz continuous on \mathbb{R}^d .*

Proof. We first note that if $\lambda_k(\Omega^*) > \lambda_{k-1}(\Omega^*)$, then the claim follows by Lemma 4.6. Suppose now that $\lambda_k(\Omega^*) = \lambda_{k-1}(\Omega^*)$. For every $\varepsilon \in (0, 1)$ consider the problem

$$\min \left\{ (1 - \varepsilon)\lambda_k(\Omega) + \varepsilon\lambda_{k-1}(\Omega) + 2\Lambda|\Omega| : \Omega \supset \Omega^* \right\}. \quad (5.1)$$

We consider the following two cases:

- (i) Suppose that there is a sequence $\varepsilon_n \rightarrow 0$ and a sequence Ω_{ε_n} of corresponding minimizers for (5.1) such that $\lambda_k(\Omega_{\varepsilon_n}) > \lambda_{k-1}(\Omega_{\varepsilon_n})$. For each $n \in \mathbb{N}$, Ω_{ε_n} is a shape supersolution for the functional $\lambda_k + 2(1 - \varepsilon_n)^{-1}\Lambda|\cdot|$ and so, by Lemma 4.6, we have that for each $n \in \mathbb{N}$ the normalized eigenfunctions $u_k^n \in \widetilde{H}_0^1(\Omega_{\varepsilon_n})$, corresponding to $\lambda_k(\Omega_{\varepsilon_n})$, are Lipschitz continuous on \mathbb{R}^d . We now prove that Ω_{ε_n} γ -converges to Ω^* as $n \rightarrow \infty$. Indeed, by [9, Proposition 5.12], Ω_{ε_n} are all contained in some ball B_R with R big enough. Thus, there is a weak- γ -convergent subsequence of Ω_{ε_n} and let $\widetilde{\Omega}$ be its limit. Then $\widetilde{\Omega}$ is a solution of the problem

$$\min \left\{ \lambda_k(\Omega) + 2\Lambda|\Omega| : \Omega \supset \Omega^* \right\}. \quad (5.2)$$

On the other hand, by Remark 5.2 we have that Ω^* is the unique solution of (5.2) and so, $\widetilde{\Omega} = \Omega^*$. Since the weak γ -limit Ω^* satisfies $\Omega^* \subset \Omega_{\varepsilon_n}$ for every $n \in \mathbb{N}$, then Ω_{ε_n} γ -converges to Ω^* . By the metrizable of the γ -convergence, we have that Ω^* is the γ -limit of Ω_{ε_n} as $n \rightarrow \infty$. As a consequence, we have that $\lambda_k(\Omega_{\varepsilon_n}) \rightarrow \lambda_k(\Omega^*)$ and by Remark 3.8 we have that the sequence u_k^n is uniformly Lipschitz.

Then, we can suppose that, up to a subsequence $u_k^n \rightarrow u$ uniformly and weakly in $H_0^1(B_R)$, for some $u \in H_0^1(B_R)$, Lipschitz continuous on \mathbb{R}^d . By the weak convergence of u_k^n , we have that for each $v \in H_0^1(\Omega^*)$

$$\int \nabla u \cdot \nabla v \, dx = \lim_{n \rightarrow \infty} \int \nabla u_k^n \cdot \nabla v \, dx = \lim_{n \rightarrow \infty} \lambda_k(\Omega_{\varepsilon_n}) \int u_k^n v \, dx = \lambda_k(\Omega^*) \int uv \, dx.$$

By the γ -convergence of Ω_{ε_n} , we have that $u \in H_0^1(\Omega^*)$ and so u is a k^{th} eigenfunction of the Dirichlet Laplacian on Ω^* .

- (ii) Suppose that there is some $\varepsilon_0 \in (0, 1)$ such that Ω_{ε_0} is a solution of (5.1) and $\lambda_k(\Omega_{\varepsilon_0}) = \lambda_{k-1}(\Omega_{\varepsilon_0})$. Then, Ω_{ε_0} is also a solution of (5.2) and, by Remark 5.2, $\Omega_{\varepsilon_0} = \Omega^*$. Thus we obtain that Ω^* is a shape supersolution for $\lambda_{k-1} + 2\varepsilon_0^{-1}\Lambda|\cdot|$. If we have

$$\lambda_k(\Omega^*) = \lambda_{k-1}(\Omega^*) > \lambda_{k-2}(\Omega^*),$$

then, we apply Lemma 4.6 obtaining that each eigenfunction corresponding to $\lambda_{k-1}(\Omega^*)$ is Lipschitz continuous on \mathbb{R}^d . On the other hand, if

$$\lambda_k(\Omega^*) = \lambda_{k-1}(\Omega^*) = \lambda_{k-2}(\Omega^*),$$

then we consider, for each $\varepsilon \in (0, 1)$, the problem

$$\min \left\{ (1 - \varepsilon_0)\lambda_k(\Omega) + \varepsilon_0[(1 - \varepsilon)\lambda_{k-1}(\Omega) + \varepsilon\lambda_{k-2}(\Omega)] + 3\Lambda|\Omega| : \Omega \supset \Omega^* \right\}. \quad (5.3)$$

One of the following two situations may occur:

- (a) There is a sequence $\varepsilon_n \rightarrow 0$ and a corresponding sequence Ω_{ε_n} of minimizers of (5.3) such that

$$\lambda_{k-1}(\Omega_{\varepsilon_n}) > \lambda_{k-2}(\Omega_{\varepsilon_n}).$$

- (b) There is some $\varepsilon_1 \in (0, 1)$ and Ω_{ε_1} , solution of (5.3), such that

$$\lambda_{k-1}(\Omega_{\varepsilon_1}) = \lambda_{k-2}(\Omega_{\varepsilon_1}).$$

If the case (a) occurs, then since Ω_{ε_n} is a shape quasi-minimizer for λ_{k-1} , by Lemma 4.6 we obtain the Lipschitz continuity of the eigenfunctions u_{k-1}^n , corresponding to λ_{k-1} on Ω_{ε_n} . Repeating the argument from (i), we obtain that Ω_{ε_n} γ -converges to Ω^* and that the sequence of eigenfunctions $u_{k-1}^n \in H_0^1(\Omega_{\varepsilon_n})$ uniformly converges to an eigenfunction $u_{k-1} \in H_0^1(\Omega^*)$, corresponding to $\lambda_k(\Omega^*) = \lambda_{k-1}(\Omega^*)$. Since the Lipschitz constants of u_{k-1}^n are uniform, we have the conclusion.

If the case (b) occurs, then reasoning as in the case (ii), we have that $\Omega_{\varepsilon_1} = \Omega^*$. Indeed, we have

$$\begin{aligned} & (1 - \varepsilon_0)\lambda_k(\Omega_{\varepsilon_1}) + \varepsilon_0\lambda_{k-1}(\Omega_{\varepsilon_1}) + 3\Lambda|\Omega_{\varepsilon_1}| \\ &= (1 - \varepsilon_0)\lambda_k(\Omega_{\varepsilon_1}) + \varepsilon_0[(1 - \varepsilon_1)\lambda_{k-1}(\Omega_{\varepsilon_1}) + \varepsilon_1\lambda_{k-2}(\Omega_{\varepsilon_1})] + 3\Lambda|\Omega_{\varepsilon_1}| \\ &\leq (1 - \varepsilon_0)\lambda_k(\Omega^*) + \varepsilon_0[(1 - \varepsilon_1)\lambda_{k-1}(\Omega^*) + \varepsilon_1\lambda_{k-2}(\Omega^*)] + 3\Lambda|\Omega^*| \\ &= (1 - \varepsilon_0)\lambda_k(\Omega^*) + \varepsilon_0\lambda_{k-1}(\Omega^*) + 3\Lambda|\Omega^*|. \end{aligned} \quad (5.4)$$

On the other hand, we supposed that Ω^* is a solution of (5.1) with $\varepsilon = \varepsilon_0$ and so, it is the unique minimizer of the problem

$$\min \left\{ (1 - \varepsilon_0)\lambda_k(\Omega) + \varepsilon_0\lambda_{k-1}(\Omega) + 3\Lambda|\Omega| : \Omega \supset \Omega^* \right\}. \quad (5.5)$$

Thus, we have $\Omega^* = \Omega_{\varepsilon_1}$. We proceed considering, for any $\varepsilon \in (0, 1)$, the problem

$$\begin{aligned} & \min \left\{ (1 - \varepsilon_0)\lambda_k(\Omega) + \varepsilon_0(1 - \varepsilon_1)\lambda_{k-1}(\Omega) \right. \\ & \quad \left. + \varepsilon_0\varepsilon_1[(1 - \varepsilon)\lambda_{k-2}(\Omega) + \varepsilon\lambda_{k-3}(\Omega)] + 4\Lambda|\Omega| : \Omega \supset \Omega^* \right\}, \end{aligned} \quad (5.6)$$

and repeat the procedure described above. We note that this procedure stops after at most k iterations. Indeed, if Ω^* is a shape quasi-minimizer for λ_1 and $\lambda_k(\Omega^*) = \dots = \lambda_1(\Omega^*)$, then we obtain the result applying Lemma 4.6 for $k = 1$.

□

As a consequence, we obtain the following result for the optimal set for the k^{th} Dirichlet eigenvalue.

Corollary 5.4. *Let Ω be a solution of the problem*

$$\min \left\{ \lambda_k(\Omega) : \Omega \subset \mathbb{R}^d, \Omega \text{ quasi-open}, |\Omega| = 1 \right\}.$$

Then there exists an eigenfunction $u_k \in H_0^1(\Omega)$, corresponding to the eigenvalue $\lambda_k(\Omega)$, which is Lipschitz continuous on \mathbb{R}^d .

Remark 5.5. *We note that Theorem 5.3 can be used to obtain information for the supersolutions of general spectral functionals. Let $\mathcal{F} : \mathcal{A} \rightarrow \mathbb{R}$ be a functional defined on the family of sets of finite measure \mathcal{A} and suppose that there exist non-negative real numbers c_k , $k \in \mathbb{N}$, such that for each couple of sets $\Omega \subset \tilde{\Omega} \subset \mathbb{R}^d$ of finite measure we have*

$$c_k(\lambda_k(\Omega) - \lambda_k(\tilde{\Omega})) \leq \mathcal{F}(\Omega) - \mathcal{F}(\tilde{\Omega}).$$

If Ω is a shape supersolution for $\mathcal{F} + \Lambda|\cdot|$, then for any $k \in \mathbb{N}$ such that $c_k > 0$, there is an eigenfunction $u_k \in H_0^1(\Omega)$, normalized in L^2 and corresponding to $\lambda_k(\Omega)$, which is Lipschitz continuous on \mathbb{R}^d . Indeed, it is enough to note that, whenever $c_k > 0$, we have

$$\lambda_k(\Omega) - \lambda_k(\tilde{\Omega}) \leq c_k^{-1} \left(\mathcal{F}(\Omega) - \mathcal{F}(\tilde{\Omega}) \right) \leq c_k^{-1} \Lambda |\tilde{\Omega} \setminus \Omega|.$$

The conclusion follows by Theorem 5.3.

In order to prove a regularity result which involves all the eigenfunction corresponding to the eigenvalues that appear in functionals of the form $F(\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega))$, we need the following preliminary result.

Lemma 5.6. *Let $\Omega^* \subset \mathbb{R}^d$ be a shape supersolution for the functional*

$$\Omega \mapsto \lambda_k(\Omega) + \lambda_{k+1}(\Omega) + \dots + \lambda_{k+p}(\Omega) + \Lambda|\Omega|,$$

for some constant $\Lambda > 0$. Then there are L^2 -orthonormal eigenfunctions $u_k, \dots, u_{k+p} \in \tilde{H}_0^1(\Omega^*)$, corresponding to the eigenvalues $\lambda_k(\Omega^*), \dots, \lambda_{k+p}(\Omega^*)$, which are Lipschitz continuous on \mathbb{R}^d .

Proof. We prove the lemma in two steps.

Step 1. Suppose that $\lambda_k(\Omega^*) > \lambda_{k-1}(\Omega^*)$. We first note that, by Lemma 4.6, if $j \in \{k, k+1, \dots, k+p\}$ is such that $\lambda_j(\Omega^*) > \lambda_{j-1}(\Omega^*)$, then any eigenfunction, corresponding to the eigenvalue $\lambda_j(\Omega^*)$, is Lipschitz continuous on \mathbb{R}^d . Let us now divide the eigenvalues $\lambda_k(\Omega^*), \dots, \lambda_{k+p}(\Omega^*)$ into clusters of equal consecutive eigenvalues. There exists $k = k_1 < k_2 < \dots < k_s \leq k+p$ such that

$$\begin{aligned} \lambda_{k-1}(\Omega^*) &< \lambda_{k_1}(\Omega^*) = \dots = \lambda_{k_2-1}(\Omega^*) \\ &< \lambda_{k_2}(\Omega^*) = \dots = \lambda_{k_3-1}(\Omega^*) \\ &\dots \\ &< \lambda_{k_s}(\Omega^*) = \dots = \lambda_{k+p}(\Omega^*). \end{aligned}$$

Then, by the above observation, the eigenspaces corresponding to the eigenvalues

$$\lambda_{k_1}(\Omega^*), \lambda_{k_2}(\Omega^*), \dots, \lambda_{k+p}(\Omega^*),$$

consist on Lipschitz continuous functions. In particular, there exists a sequence of consecutive eigenfunctions u_k, \dots, u_{k+p} satisfying the claim of the lemma.

Step 2. Suppose now that $\lambda_k(\Omega^*) = \lambda_{k-1}(\Omega^*)$. For each $\varepsilon \in (0, 1)$ we consider the problem

$$\min \left\{ \sum_{j=1}^p \lambda_{k+j}(\Omega) + (1-\varepsilon)\lambda_k(\Omega) + \varepsilon\lambda_{k-1}(\Omega) + 2\Lambda|\Omega| : \Omega^* \subset \Omega \subset \mathbb{R}^d \right\}. \quad (5.7)$$

As in Theorem 5.3, we have that at least one of the following cases occur:

- (i) There is a sequence $\varepsilon_n \rightarrow 0$ and a corresponding sequence Ω_{ε_n} of minimizers of (5.7) such that, for each $n \in \mathbb{N}$,

$$\lambda_k(\Omega_{\varepsilon_n}) > \lambda_{k-1}(\Omega_{\varepsilon_n}).$$

- (ii) There is some $\varepsilon_0 \in (0, 1)$ for which there is Ω_{ε_0} a solution of (5.7) such that

$$\lambda_k(\Omega_{\varepsilon_0}) = \lambda_{k-1}(\Omega_{\varepsilon_0}).$$

In the first case Ω_{ε_n} is a shape supersolution for the functional

$$\Omega \mapsto \lambda_k(\Omega) + \cdots + \lambda_{k+p}(\Omega) + (1 - \varepsilon_n)^{-1} \Lambda |\Omega|.$$

Thus, by *Step 1*, there are orthonormal eigenfunctions $u_k^n, \dots, u_{k+p}^n \in H_0^1(\Omega_{\varepsilon_n})$, which are Lipschitz continuous on \mathbb{R}^d . Using the same approximation argument from Theorem 5.3, we obtain the claim. In the second case, reasoning again as in Theorem 5.3, we have that $\Omega_{\varepsilon_0} = \Omega^*$ and we have to consider two more cases. If $\lambda_{k-1}(\Omega^*) > \lambda_{k-2}(\Omega^*)$, we have the claim by *Step 1*. If $\lambda_{k-1}(\Omega^*) = \lambda_{k-2}(\Omega^*)$, then we consider the problem

$$\min \left\{ \sum_{j=1}^p \lambda_{k+j}(\Omega) + (1 - \varepsilon_0) \lambda_k(\Omega) + \varepsilon_0 [(1 - \varepsilon) \lambda_{k-1}(\Omega) + \varepsilon \lambda_{k-2}(\Omega)] + 3\Lambda |\Omega| : \Omega^* \subset \Omega \subset \mathbb{R}^d \right\},$$

and proceed by repeating the argument above, until we obtain the claim or until we have a functional involving λ_1 , in which case we apply one more time the result from *Step 1*. \square

Before we state our main result (Theorem 5.7), we recall that:

- for two points $x := (x_1, \dots, x_p) \in \mathbb{R}^p$ and $y := (y_1, \dots, y_p) \in \mathbb{R}^p$, we say that $x \geq y$ if and only if $x_i \geq y_i$, for all $i = 1, \dots, p$.
- we say that a functions $F : \mathbb{R}^p \rightarrow \mathbb{R}$ is *bi-Lipschitz in each variable*, if F is Lipschitz and there are positive real constants $c_1, \dots, c_p \in (0, +\infty)$ such that

$$F(x) - F(y) \geq c_1(x_1 - y_1) + \cdots + c_p(x_p - y_p), \quad \forall x, y \in \mathbb{R}^p \text{ s.t. } x \geq y. \quad (5.8)$$

- we say that we say $F : \mathbb{R}^p \rightarrow \mathbb{R}$ is *locally bi-Lipschitz in each variable*, if the inequality (5.8) holds for each y in a neighbourhood of x .

Theorem 5.7. *Let $F : \mathbb{R}^p \rightarrow \mathbb{R}$ be an increasing and locally bi-Lipschitz function in each variable and let $0 < k_1 < k_2 < \cdots < k_p$ be natural numbers. Then for every bounded shape supersolution Ω^* of the functional*

$$\Omega \mapsto F(\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega)) + \Lambda |\Omega|,$$

there exists a sequence of orthonormal eigenfunctions u_{k_1}, \dots, u_{k_p} , corresponding to the eigenvalues $\lambda_{k_j}(\Omega^)$, $j = 1, \dots, p$, which are Lipschitz continuous on \mathbb{R}^d . Moreover,*

- *if for some k_j we have $\lambda_{k_j}(\Omega^*) > \lambda_{k_{j-1}}(\Omega^*)$, then the full eigenspace corresponding to $\lambda_{k_j}(\Omega^*)$ consists only on Lipschitz functions;*
- *if $\lambda_{k_j}(\Omega^*) = \lambda_{k_{j-1}}(\Omega^*)$, then there exist at least $k_j - k_{j-1} + 1$ orthonormal Lipschitz eigenfunctions corresponding to $\lambda_{k_j}(\Omega^*)$.*

Proof. Let $c_1, \dots, c_p \in \mathbb{R}^+$ be the strictly positive real numbers from (5.8) We note that if Ω^* is a supersolution of $F(\lambda_{k_1}, \dots, \lambda_{k_p})$, then Ω^* is also a supersolution for the functional

$$\tilde{F} = \left[\min_{j \in \{1, \dots, p\}} c_j \right] (\lambda_{k_1} + \cdots + \lambda_{k_p}),$$

and, since $\min_{j \in \{1, \dots, p\}} c_j > 0$, we can assume $\min_{j \in \{1, \dots, p\}} c_j = 1$.

Reasoning as in Lemma 5.6, we divide the family $(\lambda_{k_1}(\Omega^*), \dots, \lambda_{k_p}(\Omega^*))$ into clusters of equal eigenvalues with consecutive indexes. There exist $1 \leq i_1 < i_2 \cdots < i_s \leq p-1$ such that

$$\begin{aligned} \lambda_{k_1}(\Omega^*) &= \cdots = \lambda_{k_{i_1}}(\Omega^*) < \lambda_{k_{(i_1+1)}}(\Omega^*) = \cdots = \lambda_{k_{i_2}}(\Omega^*) \\ &< \lambda_{k_{(i_2+1)}}(\Omega^*) = \cdots = \lambda_{k_{i_3}}(\Omega^*) \\ &\cdots \\ &< \lambda_{k_{(i_s+1)}}(\Omega^*) = \cdots = \lambda_{k_p}(\Omega^*). \end{aligned}$$

Since the eigenspaces, corresponding to different clusters, are orthogonal to each other, it is enough to prove the claim for the functionals defined as the sum of the eigenvalues in each cluster. In other words, it is sufficient to restrict our attention only to the case when Ω^* is a supersolution for the functional $F(\lambda_{k_1}, \dots, \lambda_{k_p}) + \Lambda|\cdot| := \sum_{j=1}^p \lambda_{k_j} + \Lambda|\cdot|$ and is such that

$$\lambda_{k_1}(\Omega^*) = \cdots = \lambda_{k_p}(\Omega^*). \quad (5.9)$$

Moreover, in this case Ω^* is also a shape supersolution (with possibly different constant Λ) for the sum of consecutive eigenvalues $\sum_{k=k_1}^{k_p} \lambda_k + \Lambda|\cdot|$. Indeed, it is enough to consider the functional

$$\tilde{F}(\Omega) = \frac{1}{2} \sum_{j=1}^p \lambda_{k_j}(\Omega) + \theta \sum_{k=k_1}^{k_p} \lambda_k(\Omega),$$

for a suitable value of θ (e.g. $\theta = \frac{1}{2(k_p - k_1 + 1)}$). The conclusion then follows by Lemma 5.6. \square

6 Optimal sets for functionals depending on the first k eigenvalues

In this last Section we aim to show that, at least for some specific functionals, we can conclude that a minimizer is actually equivalent to an open set. All the following results are, essentially, consequences of Theorem 5.7.

Theorem 6.1. *Let $F : \mathbb{R}^k \rightarrow \mathbb{R}$ be an increasing function locally bi-Lipschitz in each variable. Then every solution Ω^* of the problem*

$$\min \left\{ F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) : \Omega \subset \mathbb{R}^d \text{ measurable, } |\Omega| = 1 \right\}, \quad (6.1)$$

is an open set. Moreover, the eigenfunctions of the Dirichlet Laplacian on Ω^ , corresponding to the eigenvalues $\lambda_1(\Omega^*), \dots, \lambda_k(\Omega^*)$, are Lipschitz continuous on \mathbb{R}^d .*

Proof. We first note that the existence of a solution of (6.1) follows by the results from [7] and [24]. Then, we prove that every solution Ω^* is a local shape supersolution of the functional

$$\Omega \mapsto F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) + \Lambda|\Omega|,$$

for some suitably chosen $\Lambda > 0$. Indeed, let $\Omega^* \subset \Omega$ and let $t := \left(\frac{|\Omega|}{|\Omega^*|} \right)^{1/d} > 1$. By the

optimality of Ω^* , we have

$$\begin{aligned}
F(\lambda_1(\Omega^*), \dots, \lambda_k(\Omega^*)) &\leq F(\lambda_1(\Omega/t), \dots, \lambda_k(\Omega/t)) \\
&\leq F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) \\
&\quad + \left(F(t^2\lambda_1(\Omega), \dots, t^2\lambda_k(\Omega)) - F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) \right) \\
&\leq F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) + \text{Lip}(F)(t^2 - 1) \sum_{i=1}^k \lambda_i(\Omega) \\
&\leq F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) + \text{Lip}(F)(t^d - 1) \sum_{i=1}^k \lambda_i(\Omega^*) \\
&\leq F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) + \text{Lip}(F) \left(\sum_{i=1}^k \lambda_i(\Omega^*) \right) |\Omega^*|^{-1} (|\Omega| - |\Omega^*|),
\end{aligned}$$

where $\text{Lip}(F)$ is the Lipschitz constant of F and we finally set $\Lambda := \frac{\text{Lip}(F)}{|\Omega^*|} \left(\sum_{i=1}^k \lambda_i(\Omega^*) \right)$.

Now the Lipschitz continuity of the eigenfunctions u_1, \dots, u_k on Ω^* follows by Theorem 5.7. The openness of the set Ω^* follows by the observation that the set

$$\Omega^{**} := \bigcup_{i=1}^k \{u_k \neq 0\} \subset \Omega^*,$$

is open and has the same eigenvalues, up to order k , as Ω^* . By the optimality of Ω^* we have $|\Omega^* \Delta \Omega^{**}| = 0$. \square

Remark 6.2. *The openness of the optimal set from Theorem 5.7 can also be obtained reasoning on each connected component of Ω^* and applying the Alt-Caffarelli technique from [1] for the functional $\lambda_1(\Omega) + \Lambda|\Omega|$ as in [5] and [9].*

Remark 6.3. *In two dimensions, it is possible to obtain the continuity of the eigenfunctions from Theorem 6.1 by a more direct method involving only elementary tools (see [23]). Roughly speaking, using the argument from Remark A.4, one can prove that in each level set of some of the eigenfunctions, there cannot be holes of small diameter, since otherwise it is more convenient to “fill” them. More precisely, for every $\xi > 0$ and every $x \in \mathbb{R}^2$ such that $u_1^2(x) + \dots + u_k^2(x) > \xi$ there is a constant $r = r(\xi) > 0$ and a ball, of radius $r(\xi)$ and centred in x , which is entirely contained in Ω^* . In particular, this fact provides an estimate on the modulus of continuity of the function $U := u_1^2 + \dots + u_k^2$ on the boundary of Ω^* .*

By the definition of the open set Ω^{**} , we have that the first k elements of the spectrum of the Dirichlet Laplacian, defined on the space $\tilde{H}_0^1(\Omega^{**})$, and those, defined on the classical Sobolev space $H_0^1(\Omega^{**})$, coincide. Thus, we have a solution of the shape optimization problem (6.1) in its classical formulation.

Corollary 6.4. *Let $F : \mathbb{R}^k \rightarrow \mathbb{R}$ be an increasing function locally bi-Lipschitz in each variable. Then there is a solution Ω^* of the problem*

$$\min \left\{ F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) : \Omega \subset \mathbb{R}^d \text{ open, } |\Omega| = 1 \right\}. \quad (6.2)$$

Moreover, the eigenfunctions of the Dirichlet Laplacian on Ω^ , corresponding to the eigenvalues $\lambda_1(\Omega^*), \dots, \lambda_k(\Omega^*)$, are Lipschitz continuous on \mathbb{R}^d .*

Remark 6.5. *Theorem 6.1 and Corollary 6.4 apply, in particular, to the functional*

$$F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) := \sum_{i=1}^k \lambda_i(\Omega).$$

In Theorem 6.1 we proved that every solution of (6.1) contains another solution, which is an open set. The analogous result holds also for supersolutions.

Proposition 6.6. *Let $F : \mathbb{R}^k \rightarrow \mathbb{R}$ be an increasing locally bi-Lipschitz function in each variable and Ω^* be a subsolution for the functional*

$$\Omega \mapsto F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) + \Lambda|\Omega|. \quad (6.3)$$

Then

- (i) *There are eigenfunctions $u_1, \dots, u_k \in \tilde{H}_0^1(\Omega^*)$, corresponding to the eigenvalues $\lambda_1(\Omega^*), \dots, \lambda_k(\Omega^*)$, which are Lipschitz continuous on \mathbb{R}^d .*
- (ii) *There is an open set $\Omega^{**} \subset \Omega^*$ such that $u_1, \dots, u_k \in H_0^1(\Omega^{**})$; $\lambda_i(\Omega^{**}) = \lambda_i(\Omega^*)$, for every $i = 1, \dots, k$; Ω^{**} is still a supersolution for the functional (6.3).*

Proof. The first claim follows from Theorem 5.7. For (ii) we define Ω^{**} as in Theorem 6.1:

$$\Omega^{**} := \bigcup_{i=1}^k \{u_i \neq 0\},$$

thus we have $\lambda_i(\Omega^*) = \lambda_i(\Omega^{**})$ for every $i = 1, \dots, k$. For all $\Omega \supset \Omega^{**}$ we compute

$$\begin{aligned} F(\lambda_1(\Omega^{**}), \dots, \lambda_k(\Omega^{**})) + \Lambda|\Omega^{**}| + \Lambda|\Omega^* \setminus \Omega^{**}| &= F(\lambda_1(\Omega^*), \dots, \lambda_k(\Omega^*)) + \Lambda|\Omega^*| \\ &\leq F(\lambda_1(\Omega \cup \Omega^*), \dots, \lambda_k(\Omega \cup \Omega^*)) + \Lambda|\Omega \cup \Omega^*| \\ &\leq F(\lambda_1(\Omega), \dots, \lambda_k(\Omega)) + \Lambda|\Omega| + \Lambda|\Omega^* \setminus \Omega^{**}|, \end{aligned}$$

hence Ω^{**} is also a supersolution for (6.3). □

For functionals of the form

$$\Omega \mapsto F(\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega)),$$

depending on some non-consecutive eigenvalues $\lambda_{k_1}, \dots, \lambda_{k_p}$, it is still possible to obtain that an optimal set Ω^* for the problem

$$\min \left\{ F(\lambda_{k_1}(\Omega), \dots, \lambda_{k_p}(\Omega)) : \Omega \subset \mathbb{R}^d \text{ measurable, } |\Omega| = 1 \right\}, \quad (6.4)$$

is open, provided that an additional condition on the eigenvalues of Ω^* is satisfied.

Proposition 6.7. *Let $F : \mathbb{R}^p \rightarrow \mathbb{R}$ be an increasing and locally bi-Lipschitz function in each variable, $0 < k_1 < k_2 < \dots < k_p$ be natural numbers and Ω^* a minimizer for the problem (6.4). If for all $j = 1, \dots, p$ we have $\lambda_{k_j}(\Omega^*) > \lambda_{k_{j-1}}(\Omega^*)$ then the set Ω^* is open. Moreover all the eigenfunctions corresponding to $\lambda_{k_j}(\Omega^*)$, for all $j = 1, \dots, p$ are Lipschitz continuous on \mathbb{R}^d .*

Proof. The second part of the claim follows by Theorem 5.7. In order to prove the openness of Ω^* we consider the family of indices

$$I := \left\{ i \in \mathbb{N} : \lambda_i(\Omega^*) = \lambda_{k_j}(\Omega^*), \text{ for some } j \right\},$$

and the set

$$\Omega_A := \left\{ x \in \mathbb{R}^d : \sum_{i \in I} u_i(x)^2 > 0 \right\}.$$

We aim to prove that the set $N := \Omega^* \setminus \Omega_A$ has zero Lebesgue measure. Suppose, by contradiction, that $|N| > 0$ and let $x \in N$ be a point of density one for N , i.e.

$$\lim_{\rho \rightarrow 0} \frac{|N \cap B_\rho(x)|}{|B_\rho(x)|} = 1. \quad (6.5)$$

Since, for $\rho \rightarrow 0$, the sets $\Omega^* \setminus (N \cap B_\rho(x))$ γ -converge to Ω^* we have the convergence of the spectra $\lambda_k(\Omega^* \setminus (N \cap B_\rho(x))) \rightarrow \lambda_k(\Omega^*)$, for every $k \in \mathbb{N}$.

Since $\lambda_{k_j}(\Omega^*) > \lambda_{k_j-1}(\Omega^*)$, we can choose ρ small enough such that the new set $\tilde{\Omega} := \Omega^* \setminus (N \cap B_\rho(x))$ satisfies

$$\lambda_i(\tilde{\Omega}) < \lambda_{k_j}(\Omega^*), \quad \forall i = 1, \dots, k_j - 1. \quad (6.6)$$

We now note that for $i \in I$ the eigenfunction $u_i \in \tilde{H}_0^1(\tilde{\Omega})$ and since $\tilde{\Omega} \subset \Omega^*$, we get that u_i satisfies the equation

$$-\Delta u_i = \lambda_{k_j}(\Omega^*) u_i, \quad u_i \in \tilde{H}_0^1(\tilde{\Omega}).$$

Thus, for $i \in I$, the number $\lambda_i(\Omega^*)$ is also in the spectrum of the Dirichlet Laplacian on $\tilde{\Omega}$. Combined with (6.6) this gives

$$\lambda_k(\tilde{\Omega}) \leq \lambda_k(\Omega^*), \quad \forall k = 1, \dots, k_p. \quad (6.7)$$

Since for $\rho > 0$ small enough $|N \cap B_\rho(x)| > 0$, we have that $|\tilde{\Omega}| < |\Omega^*|$. By the strict monotonicity of F , we can rescale $\tilde{\Omega}$ thus obtaining a better competitor than Ω^* in (6.4), which is a contradiction with the optimality of Ω^* . \square

Remark 6.8. Unfortunately, Proposition 6.7 provides the openness of optimal sets only up to zero Lebesgue measure. Hence we have that $\tilde{H}_0^1(\Omega^*) = \tilde{H}_0^1(\Omega_A)$, but we do not know in general if $H_0^1(\Omega^*) = H_0^1(\Omega_A)$.

A Appendix: Proof of Theorem 3.6

For the sake of the completeness, we report here the proof of Theorem 3.6, given in [6]. We note that if the state function u , quasi-minimizer for the functional J_f , is positive, then the classical approach of Alt and Caffarelli (see [1]) can be applied to obtain the Lipschitz continuity of u . This approach is based on an external perturbation and on the following inequality (see [1, Lemma 3.2])

$$\frac{|B_r(x_0) \cap \{u = 0\}|}{r^2} \left(\int_{\partial B_r(x_0)} u d\mathcal{H}^{d-1} \right)^2 \leq C_d \int_{B_r(x_0)} |\nabla(u - v)|^2 dx, \quad (A.1)$$

which holds for every $x_0 \in \mathbb{R}^d$, $r > 0$, $u \in H^1(\mathbb{R}^d)$, $u \geq 0$ and $v \in H^1(B_r)$ that solves

$$\min \left\{ \int_{B_r(x_0)} |\nabla v|^2 dx : v - u \in H_0^1(B_r(x_0)), v \geq u \right\}. \quad (A.2)$$

Since for sign-changing state functions u , the inequality (A.1) is not known, one needs a more careful analysis on the common boundary of $\{u > 0\}$ and $\{u < 0\}$, which is based on the monotonicity formula of Alt-Caffarelli-Friedmann.

Theorem A.1. *Let $U^+, U^- \in H^1(B_1)$ be continuous non-negative functions such that $\Delta U^\pm \geq -1$ on B_1 and $U^+U^- = 0$. Then there is a dimensional constant C_d such that for each $r \in (0, \frac{1}{2})$*

$$\left(\frac{1}{r^2} \int_{B_r} \frac{|\nabla U^+(x)|^2}{|x|^{d-2}} dx \right) \left(\frac{1}{r^2} \int_{B_r} \frac{|\nabla U^-(x)|^2}{|x|^{d-2}} dx \right) \leq C_d \left(1 + \int_{B_1} |U^+ + U^-|^2 dx \right). \quad (\text{A.3})$$

For our purposes we will need the following rescaled version of this formula.

Corollary A.2. *Let $\Omega \subset \mathbb{R}^d$ be a quasi-open set of finite measure, $f \in L^\infty(\Omega)$ and $u : \mathbb{R}^d \rightarrow \mathbb{R}$ be a continuous function such that*

$$-\Delta u = f \quad \text{in } \Omega, \quad u \in H_0^1(\Omega). \quad (\text{A.4})$$

Setting $u^+ = \sup\{u, 0\}$ and $u^- = \sup\{-u, 0\}$, there is a dimensional constant C_d such that for each $0 < r \leq 1/2$

$$\left(\frac{1}{r^2} \int_{B_r} \frac{|\nabla u^+(x)|^2}{|x|^{d-2}} dx \right) \left(\frac{1}{r^2} \int_{B_r} \frac{|\nabla u^-(x)|^2}{|x|^{d-2}} dx \right) \leq C_d \left(\|f\|_\infty^2 + \int_\Omega u^2 dx \right) \leq C_m, \quad (\text{A.5})$$

where $C_m = C_d \|f\|_\infty^2 \left(1 + |\Omega|^{\frac{d+4}{d}} \right)$.

Proof. We apply Theorem A.1 to $U^\pm = \|f\|_\infty^{-1} u^\pm$ and substituting in (A.3) we obtain the first inequality in (A.5). The second one follows, using the equation (A.4):

$$\|u\|_{L^2}^2 \leq C_d |\Omega|^{2/d} \|\nabla u\|_{L^2}^2 = C_d |\Omega|^{2/d} \int_\Omega f u dx \leq C_d |\Omega|^{2/d+1/2} \|f\|_\infty \|u\|_{L^2}. \quad (\text{A.6})$$

□

The proof of the Lipschitz continuity of the quasi-minimizers for J_f needs two preliminary results, precisely in Lemma A.3 we prove the continuity of u and in Lemma A.5, we give an estimate on the Laplacian of u as a measure on the boundary $\partial\{u \neq 0\}$.

Lemma A.3. *Suppose that u satisfies the conditions (a) and (b) from Theorem 3.6. Then u is continuous.*

Proof. Let $x_n \rightarrow x_\infty \in \mathbb{R}^d$ and set $\delta_n := |x_n - x_\infty|$. If for some n , $|B(x_\infty, \delta_n) \cap \{u = 0\}| = 0$, then $-\Delta u = f$ in $B(x_\infty, \delta_n)$ and so u is continuous in x_∞ .

Assume now that for all n , $|B(x_\infty, \delta_n) \cap \{u = 0\}| \neq 0$ and consider the function $u_n : \mathbb{R}^d \rightarrow \mathbb{R}$ defined by $u_n(\xi) = u(x_\infty + \delta_n \xi)$. Since $\|u_n\|_\infty = \|u\|_\infty$, for any n , we can assume, up to a subsequence, that u_n converges weakly-* in L^∞ to some function $u_\infty \in L^\infty(\mathbb{R}^d)$.

If we prove that $u_\infty = 0$ and that $u_n \rightarrow u_\infty$ uniformly on B_1 , then we would have that u is continuous and $u(x_\infty) = 0$.

Step 1. u_∞ is a constant.

For all $R \geq 1$ and $n \in \mathbb{N}$, we introduce the function $v_{R,n}$ such that:

$$\begin{cases} -\Delta v_{R,n} = f, & \text{in } B_{R\delta_n}(x_\infty), \\ v_{R,n} = u, & \text{on } \partial B_{R\delta_n}(x_\infty). \end{cases} \quad (\text{A.7})$$

Setting $v_n(\xi) := v_{R,n}(x_\infty + \delta_n \xi)$, we have that

$$\begin{aligned}
\int_{B_R} |\nabla(u_n - v_n)|^2 d\xi &= \delta_n^{2-d} \int_{B(x_\infty, R\delta_n)} |\nabla(u - v_{R,n})|^2 dx \\
&= \delta_n^{2-d} \int_{B(x_\infty, R\delta_n)} \nabla u \cdot \nabla(u - v_{R,n}) dx - \delta_n^{2-d} \int_{B(x_\infty, R\delta_n)} f(u - v_{R,n}) dx \\
&\leq C_b \delta_n^{2-d} \left(\int_{B(x_\infty, R\delta_n)} |\nabla(u - v_{R,n})|^2 dx \right)^{1/2} R^{d/2} \delta_n^{d/2} \\
&\leq C_b R^{d/2} \delta_n \left(\int_{B_R} |\nabla(u_n - v_n)|^2 d\xi \right)^{1/2},
\end{aligned}$$

and thus, for $\delta_n \leq r_0$, we have

$$\int_{B_R} |\nabla(u_n - v_n)|^2 d\xi \leq C_b^2 \delta_n^2, \quad (\text{A.8})$$

where C_b is the constant from (3.8). In particular, $u_n - v_n \rightarrow 0$ in $H^1(B_R)$ for any $R \geq 1$. On the other hand, we have that

$$\begin{cases} -\Delta v_n = \delta_n^2 f, & \text{in } B_R, \\ v_n \leq \|u\|_\infty, & \text{on } \partial B_R. \end{cases} \quad (\text{A.9})$$

Thus, v_n are equi-bounded (by the maximum principle) and equi-continuous (by Remark 2.3) on the ball $B_{R/2}$ and so, the sequence v_n uniformly converges to some function which is harmonic on $B_{R/2}$. By the uniqueness of the weak-* limit in L^∞ , we have that this function is precisely L^∞ . Thus, u_∞ is a harmonic function on each $B_{R/2}$ and so, on \mathbb{R}^d . Since it is bounded, it is a constant.

Step 2. $u_n \rightarrow u_\infty$ in $H_{loc}^1(\mathbb{R}^d)$.

In fact, for the functions $\tilde{v}_n = v_n - u_\infty$, we have that

$$\begin{cases} -\Delta \tilde{v}_n = \delta_n^2 f, & \text{in } B_R, \\ \tilde{v}_n \leq 2\|u\|_\infty, & \text{on } \partial B_R, \end{cases} \quad (\text{A.10})$$

and $\tilde{v}_n \rightarrow 0$ uniformly on $B_{R/2}$. By Remark 2.3, we have that $\|\nabla \tilde{v}_n\|_{L^\infty(B_{R/4})} \rightarrow 0$ and so, $v_n \rightarrow u_\infty$ in $H^1(B_{R/4})$ and the same holds for u_n .

Step 3. If $u_\infty \geq 0$, then $u_n^- \rightarrow 0$ uniformly on balls.

Since on $\{u_n < 0\}$, the equality $-\Delta u_n^- = -\delta_n^2 f$ holds, we have that $-\Delta u_n^- \leq -\delta_n^2 f I_{\{u_n < 0\}} \leq \delta_n^2 |f|$ on \mathbb{R}^d . Thus, it is enough to prove that for each $R \geq 1$, $\tilde{u}_n \rightarrow 0$ uniformly on $B_{R/2}$, where

$$\begin{cases} -\Delta \tilde{u}_n = \delta_n^2 |f|, & \text{in } B_R, \\ \tilde{u}_n = u_n^-, & \text{on } \partial B_R. \end{cases} \quad (\text{A.11})$$

Since $u_n^- \rightarrow 0$ in $H^1(B_R)$, we have that $\int_{\partial B_R} u_n^- \rightarrow 0$. Writing $\tilde{u}_n = \tilde{w}_n + \tilde{u}_h$, where $\tilde{w}_n \in H_0^1(B_R)$, $-\Delta \tilde{w}_n = \delta_n^2 |f|$ and \tilde{u}_h is the harmonic function on B_R with boundary values equal to \tilde{u}_n , we have the thesis of Step 3.

Step 4. $u_\infty = 0$

Suppose that $u_\infty \geq 0$. Let $y_n = x_\infty + \delta_n \xi_n$, where $\xi_n \in B_1$, be such that $u(y_n) = 0$. For each $s > 0$ consider the function $\phi_s \in C_c^\infty(B(y_n, 2s))$ such that $0 \leq \phi_s \leq 1$, $\phi_s = 1$ on

$B(y_n, s)$ and $\|\nabla\phi_s\|_{L^\infty} \leq \frac{C_d}{s}$, where C_d is some constant depending only on the dimension d . Thus, we have that

$$|\langle \Delta u + f, \phi_s \rangle| \leq C_d C_b s^{d-1}, \quad (\text{A.12})$$

where C is the constant from (3.8). Denote with μ_1 and μ_2 the positive Borel measures $\Delta u^+ + fI_{\{u>0\}}$ and $\Delta u^- - fI_{\{u<0\}}$. Then, we have

$$\mu_1(B_s(y_n)) \leq \langle \mu_1, \phi_s \rangle = \langle \mu_1 - \mu_2, \phi_s \rangle + \langle \mu_2, \phi_s \rangle \leq C_d C_b s^{d-1} + \mu_2(B_{2s}(y_n)). \quad (\text{A.13})$$

Moreover, since $f \in L^\infty$, we have that for each $s \leq 1$,

$$\Delta u^+(B_s(y_n)) \leq (C_d C_b + (1 + 2^d)\|f\|_\infty) s^{d-1} + \Delta u^-(B_{2s}(y_n)). \quad (\text{A.14})$$

Multiplying by s^{1-d} and integrating, we obtain

$$\int_{\partial B_{\delta_n}(y_n)} u^+ d\mathcal{H}^{d-1} \leq \frac{1}{2} \int_{\partial B_{2\delta_n}(y_n)} u^- d\mathcal{H}^{d-1} + (C_d C_b + (1 + 2^d)\|f\|_\infty) \delta_n, \quad (\text{A.15})$$

or, equivalently,

$$\int_{\partial B_1} u_n^+(\xi_n + \cdot) d\mathcal{H}^{d-1} \leq \int_{\partial B_2} u_n^-(\xi_n + \cdot) d\mathcal{H}^{d-1} + (C_d C_b + (1 + 2^d)\|f\|_\infty) \delta_n. \quad (\text{A.16})$$

Since, the right-hand side goes to zero as $n \rightarrow \infty$, so does the left-hand side. Up to a subsequence, we may assume that $\xi_n \rightarrow \xi_\infty$ and so, $u_n(\xi_n + \cdot) \rightarrow u_\infty(\xi_\infty + \cdot) = u_\infty$ in $H_{loc}^1(\mathbb{R}^d)$. Thus $u_\infty = 0$.

Step 5. The convergence $u_n \rightarrow 0$ is uniform on the ball B_1 .

We already know that $u_n \rightarrow 0$ in $H_{loc}^1(\mathbb{R}^d)$. Moreover, by the same argument as in Step 3, we have that

$$-\Delta|u_n| \leq \delta_n^2|f|, \quad (\text{A.17})$$

in \mathbb{R}^d and that $|u_n| \rightarrow 0$ uniformly on any ball. \square

Remark A.4. In \mathbb{R}^2 the continuity of the state function u , from Theorem 3.6, can be deduced by the classical Alt-Caffarelli argument, which we apply after reducing the problem to the case when u is positive. For example, if $u \in H^1(\mathbb{R}^2)$ is a function satisfying

$$J_{\lambda u}(u) + c|\{u \neq 0\}| \leq J_{\lambda u}(v) + c|\{v \neq 0\}|, \quad \forall v \in H^1(\mathbb{R}^2),$$

for some $\lambda > 0$, then u is continuous. Indeed, let $x_0 \in \mathbb{R}^d$ be such that $u(x_0) > 0$ and let $r_0 > 0$ and $\varepsilon > 0$ be small enough such that, for every $x \in \mathbb{R}^d$ and every $r \leq r_0$, we have $\int_{B_r(x)} |\nabla u|^2 dx \leq \varepsilon$. As a consequence, for every $x \in \mathbb{R}^d$ there is some $r_x \in [r_0/2, r_0]$ such that $\int_{\partial B_{r_x}(x)} |\nabla u|^2 dx \leq 2\varepsilon/r_0$ and

$$\text{osc}_{\partial B_{r_x}(x)} u \leq \int_{\partial B_{r_x}(x)} |\nabla u| d\mathcal{H}^1 \leq \sqrt{2\pi r_0} \sqrt{2\varepsilon/r_0} \leq \sqrt{4\pi\varepsilon}. \quad (\text{A.18})$$

On the other hand, the positive part $u^+ = \sup\{u, 0\}$ of u satisfies $\Delta u^+ + \lambda\|u\|_\infty \geq 0$ on \mathbb{R}^d and so, there is a constant $C > 0$ such that

$$u(x_0) \leq \int_{\partial B_{r_{x_0}}(x_0)} u d\mathcal{H}^1 + Cr_{x_0}^2,$$

which together with (A.18) gives that, choosing $r_0 > 0$ small enough, we can construct a ball $B_r(x_0)$ of radius $r \leq r_0$ such that $u \geq u(x_0)/2 > 0$ on $\partial B_r(x_0)$.

We then notice that the set $\{u < 0\} \cap B_r(x_0)$ has measure 0. Indeed, if this is not the case, then the function $\tilde{u} = \sup\{-u, 0\} \mathbb{1}_{B_r(x_0)} \in H_0^1(B_r(x_0))$ is such that $J_{\lambda u}(u) = J_{\lambda u}(-\tilde{u}) + J_{\lambda u}(u + \tilde{u})$. By the maximum principle $\|\tilde{u}\|_\infty \leq Cr_0^2$ and so, for some constant $C > 0$, we have

$$|J_{\lambda u}(-\tilde{u})| \leq Cr_0^2 |\{u < 0\} \cap B_r(x_0)| < c |\{u < 0\} \cap B_r(x_0)|,$$

for r_0 small enough. Hence we have $J_{\lambda u}(-\tilde{u}) + c |\{u < 0\} \cap B_r(x_0)| > 0$, that contradicts the quasi-minimality of u .

We conclude the proof by showing that the set $\{u = 0\} \cap B_r(x_0)$ has measure 0. We compare u with the function $w = \mathbb{1}_{B_r^c(x_0)}u + \mathbb{1}_{B_r(x_0)}v$, where v is the function from (A.2).

$$\begin{aligned} c |\{u = 0\} \cap B_r(x_0)| &\geq J_{\lambda u}(u) - J_{\lambda u}(w) \\ &= \frac{1}{2} \int_{B_r(x_0)} (|\nabla u|^2 - |\nabla v|^2) dx - \int_{B_r(x_0)} \lambda u(u - v) dx \\ &\geq \frac{1}{2} \int_{B_r(x_0)} |\nabla(u - v)|^2 dx \\ &\geq \frac{C_2}{r^2} |\{u = 0\} \cap B_r(x_0)| \left(\int_{\partial B_r(x_0)} u d\mathcal{H}^1 \right)^2, \end{aligned}$$

where the last inequality is due to (A.1). If we suppose that $|\{u = 0\} \cap B_r(x_0)| > 0$, then for some constant $C > 0$, we would have $u(x_0) \leq Cr_0^2$, which is absurd choosing $r_0 > 0$ small enough.

Lemma A.5. *Let $u \in H^1(\mathbb{R}^d)$ satisfies the conditions (a) and (b) from Theorem 3.6. Then, for each $x_0 \in \mathbb{R}^d$, in which u vanishes, and each $0 < r \leq r_0/4$, where r_0 is the constant from condition (b) in Theorem 3.6, we have that*

$$|\Delta|u|| (B_r(x_0)) \leq Cr^{d-1}, \quad (\text{A.19})$$

where the constant C is given by the expression $C = C_d(C_b + \sqrt{C_m} + 1)$, where C_d is a constant depending only on the dimension, C_b is the constant from (3.8) and C_m is the constant from the monotonicity formula (A.2).

Proof. Without loss of generality we can suppose $x_0 = 0$. For each $r > 0$, consider the functions

$$v^r := v_+^r - v_-^r, \quad w^r := w_+^r - w_-^r,$$

where v_\pm^r and w_\pm^r are solutions of the following equations on B_r

$$\begin{cases} -\Delta v_\pm^r = f^\pm, & \text{in } B_r, \\ v_\pm^r = u^\pm, & \text{on } \partial B_r, \end{cases} \quad \begin{cases} -\Delta w_\pm^r = f^\pm, & \text{in } B_r, \\ w_\pm^r = 0, & \text{on } \partial B_r. \end{cases} \quad (\text{A.20})$$

Thus we have that $v_\pm^r - w_\pm^r$ is harmonic in B_r and so, the estimate

$$\int_{B_r} |\nabla(v_\pm^r - w_\pm^r)|^2 dx \leq \int_{B_r} |\nabla u^\pm|^2 dx. \quad (\text{A.21})$$

Since $u^\pm - v_\pm^r + w_\pm^r \in H_0^1(B_r)$, we have

$$\begin{aligned} \int_{B_r} |\nabla(u^\pm - v_\pm^r + w_\pm^r)|^2 dx &= \int_{B_r} \nabla u^\pm \cdot \nabla(u^\pm - v_\pm^r + w_\pm^r) dx \\ &= \int_{B_r} |\nabla u^\pm|^2 dx + \int_{B_r} \nabla u^\pm \cdot \nabla(w_\pm^r - v_\pm^r) dx \\ &\leq 2 \int_{B_r} |\nabla u^\pm|^2 dx, \end{aligned} \quad (\text{A.22})$$

where the last inequality is due to (A.21). Thus, we obtain

$$\begin{aligned} & \left(\int_{B_r} |\nabla(u^+ - v_+^r + w_+^r)|^2 dx \right) \left(\int_{B_r} |\nabla(u^- - v_-^r + w_-^r)|^2 dx \right) \\ & \leq 4 \left(\int_{B_r} |\nabla u^+|^2 dx \right) \left(\int_{B_r} |\nabla u^-|^2 dx \right) \\ & \leq 4C_m, \end{aligned} \quad (\text{A.23})$$

where the last inequality is due to the monotonicity formula (A.2) and C_m is the constant that appears there.

On the other hand, for $0 < r \leq r_0 \leq 1$, we have

$$\begin{aligned} \int_{B_r} |\nabla(u - v^r + w^r)|^2 dx & \leq 2 \int_{B_r} |\nabla(u - v^r)|^2 dx + 2 \int_{B_r} |\nabla w^r|^2 dx \\ & = 2 \int_{B_r} [\nabla u \cdot \nabla(u - v^r) + f(u - v^r)] dx + 2 \int_{B_r} |\nabla w^r|^2 dx \\ & \leq C_b^2 r^d + C_d r^d, \end{aligned} \quad (\text{A.24})$$

where C_b is the constant from condition (b). Using (A.23) and (A.24), we have

$$\begin{aligned} & \int_{B_r} |\nabla(u^+ - v_+^r + w_+^r)|^2 dx + \int_{B_r} |\nabla(u^- - v_-^r + w_-^r)|^2 dx \\ & \leq \int_{B_r} |\nabla(u - v^r + w^r)|^2 dx \\ & \quad + 2 \left(\int_{B_r} |\nabla(u^+ - v_+^r + w_+^r)|^2 dx \right)^{1/2} \left(\int_{B_r} |\nabla(u^- - v_-^r + w_-^r)|^2 dx \right)^{1/2} \\ & \leq (C_b^2 + 4C_m + C_d) r^d. \end{aligned} \quad (\text{A.25})$$

Denoting with $C_{b,m,d}$ the constant

$$C_{b,m,d} = 2C_b^2 + 8C_m = C_d, \quad (\text{A.26})$$

we have the estimate

$$\int_{B_r} |\nabla(u^\pm - v_\pm^r)|^2 dx \leq C_{b,m,d} r^d. \quad (\text{A.27})$$

Note that $u^+ \leq v_+^r$. In fact, we have

$$\Delta(u^+ - v_+^r) = \Delta u^+ + f^+ \geq \Delta u^+ + f I_{\{u>0\}}, \quad (\text{A.28})$$

and so, $u^+ - v_+^r$ is sub-harmonic in B_r and vanishes on ∂B_r and thus, is negative. Analogously, $\Delta(u^- - v_-^r) \geq \Delta u^- - f I_{\{u<0\}}$ and $u^- \leq v_-^r$. Moreover, by (A.28) and the fact that $u^+ - v_+^r \in H_0^1(B_r)$, we have that

$$\begin{aligned} \int_{B_r} |\nabla(u^+ - v_+^r)|^2 dx & \geq \int_{B_r} -\nabla(v_+^r - u^+) \cdot \nabla u^+ + (v_+^r - u^+) f I_{\{u>0\}} dx \\ & = \int_{B_r} (v_+^r - u^+) d\mu_1 = \int_{B_r} v_+^r d\mu_1. \end{aligned} \quad (\text{A.29})$$

Applying the estimate (A.27) and setting

$$\mu_1 := \Delta u^+ + f I_{\{u>0\}}, \quad \mu_2 := \Delta u^- - f I_{\{u<0\}}, \quad (\text{A.30})$$

we have that

$$\int_{B_r} v_+^r d\mu_1 \leq C_{b,m,d} r^d, \quad \int_{B_r} v_-^r d\mu_2 \leq C_{b,m,d} r^d \quad (\text{A.31})$$

Setting $U := u^+ - v_+^r \leq 0$ on B^r , we have that for each $z \in B_{r/4}$

$$\int_{\partial B_{3r/4}(z)} U d\mathcal{H}^{d-1} \leq 0 \leq u^+(z) = U(z) + v_+^r(z). \quad (\text{A.32})$$

Applying (2.9) to $U \in H^1(B_r)$ and using (A.28), we obtain

$$\begin{aligned} v_+^r(z) &\geq \int_0^{3r/4} s^{1-d} \int_{B_s(z)} \Delta U(B_s(z)) ds \\ &\geq \int_0^{3r/4} s^{1-d} \int_{B_s(z)} \mu_1(B_s(z)) ds. \end{aligned} \quad (\text{A.33})$$

Integrating both sides of (A.33) on $B_{r/4}$ with respect to $d\mu_1(z)$, we obtain

$$\begin{aligned} C_{b,m,d}(r/4)^d &\geq \int_{B_{r/4}} v_+^r(z) d\mu_1(z) \\ &\geq \frac{1}{d\omega_d} \int_{B_{r/4}} d\mu_1(z) \int_0^{3r/4} s^{1-d} \mu_1(B_s(z)) ds \\ &\geq \frac{1}{d\omega_d} \int_{B_{r/4}} d\mu_1(z) \int_{r/2}^{3r/4} s^{1-d} \mu_1(B_s(z)) ds \\ &\geq \frac{1}{d\omega_d} \int_{B_{r/4}} d\mu_1(z) \int_{r/2}^{3r/4} s^{1-d} \mu_1(B_{r/4}) ds \\ &\geq C_d r^{2-d} [\mu_1(B_{r/4})]^2, \end{aligned} \quad (\text{A.34})$$

which proves the claim. \square

Proof of Theorem 3.6. Note that we can assume $\Omega = \{u \neq 0\}$. Since, by Lemma (4.3), $u : \mathbb{R}^d \rightarrow \mathbb{R}$ is continuous, we have that $\Omega := \{u \neq 0\}$ is open. For any $r > 0$, denote with $\Omega_r \subset \Omega$ the set $\{x \in \Omega : d(x, \Omega^c) < r\}$. Choose $x \in \omega_{r_0/2}$ and let $y \in \partial\Omega$ such that $R_x := |x - y| = d(x, \Omega^c)$. We use the gradient estimate from Remark 2.3 of u on the ball $B_{R_x}(x)$:

$$\begin{aligned} |\nabla u(x)| &\leq C_d \|f\|_{L^\infty} + \frac{2d}{R_x} \|u\|_{L^\infty(B_{R_x}(x))} \\ &\leq C_d \|f\|_{L^\infty} + \frac{2d}{R_x} \|u\|_{L^\infty(B_{2R_x}(y))} \\ &\leq (C_d + r_0) \|f\|_{L^\infty} + \frac{C_d}{R_x} \int_{\partial B_{3R_x}(y)} |u| d\mathcal{H}^{d-1} \\ &\leq (C_d + r_0) \|f\|_{L^\infty} + \frac{C_d}{R_x} \int_0^{3R_x} s^{1-d} |\Delta|u|(B_s(y)) ds \\ &\leq (C_d + r_0) \|f\|_{L^\infty} + 3C_d C, \end{aligned} \quad (\text{A.35})$$

where $C = C_d(C_b + \sqrt{C_m} + 1)$ is the constant from Lemma A.5. Since for $x \in \Omega \setminus \Omega_{r_0/2}$, we have that

$$|\nabla u(x)| \leq C_d \|f\|_{L^\infty} + \frac{4d}{r_0} \|u\|_{L^\infty}, \quad (\text{A.36})$$

we obtain that u is Lipschitz and

$$\|\nabla u\|_{L^\infty} \leq (C_d + r_0) \|f\|_\infty + C_d \max \left\{ C_b + \sqrt{C_m} + 1, \frac{\|u\|_\infty}{r_0} \right\}. \quad (\text{A.37})$$

□

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