

Innocent strategies as sheaves, and interactive equivalences for CCS

Tom Hirschowitz and Damien Pous

PPS, Février 2010



UMR 5127

Programming languages: a technology

Claim

Research in programming languages is mainly **technological**.

Applies a non-formalised method, e.g.:

- Syntax.
- Quotienting by variable renaming ($x \mapsto x = y \mapsto y$).
- Reduction relation to model program execution.
- Reasoning on reduction.

Programming languages: a technology

Claim

Research in programming languages is mainly **technological**.

Long-term goal

Contribute to finding a general setting for this.

Leads to stupid questions like:

- What is a programming language?
- What is an observational equivalence?
- What is a compilation?

Related work

- Higher-order rewriting (Nipkow, 1991), with models in cartesian closed 2-categories.
- Does not account for calculi with a structural congruence.
- Formats and their functorial interpretation by Plotkin and Turi.
- Anything else?

Outline

- A category \mathbb{E} of **executions**, with a (Grothendieck) topology on \mathbb{E} .

Innocent strategies as **sheaves**.

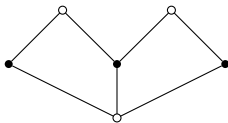
- The **stack** of strategies.

Interaction by amalgamation.

- Notions of observation.

Fair testing = must testing.

Positions

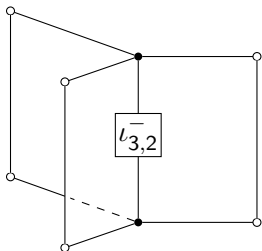


- ●'s = players,
- ○'s = channels.
- Close to (multi-hole) **active contexts** in CCS:

$$\nu abc.X_1(a, c)|X_2(a, b, c)|X_3(b, c).$$

Moves from natural deduction: in/out

$$\frac{a_0, \dots, a_{n-1} \vdash P}{a_0, \dots, a_{n-1} \vdash a_i.P}$$



$$Y$$

$$\downarrow$$

$$M$$

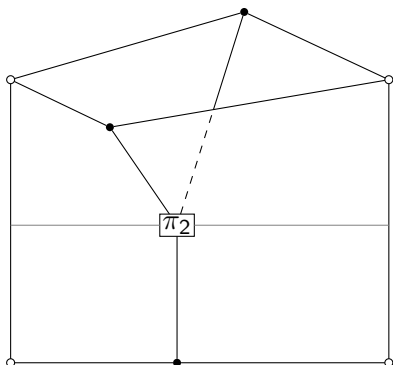
$$\uparrow$$

$$X.$$

Output: same with a $l_{n,i}^+$.

Moves from natural deduction: parallel composition

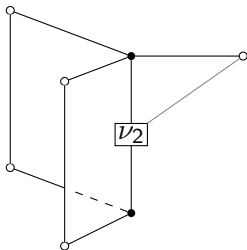
$$\frac{\Gamma \vdash P \quad \Gamma \vdash Q}{\Gamma \vdash P|Q}$$



Y
 \downarrow
 M
 \uparrow
 X .

Moves from natural deduction: name creation

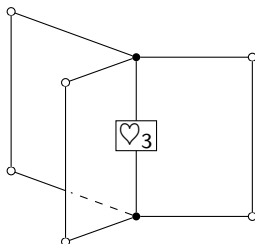
$$\frac{\Gamma, a \vdash P}{\Gamma \vdash \nu a.P}$$



$$Y \rightleftarrows M \rightleftarrows X .$$

Moves from natural deduction: tick

$$\frac{\Gamma \vdash P}{\Gamma \vdash \heartsuit.P}$$



$$Y$$

$$\downarrow$$

$$M$$

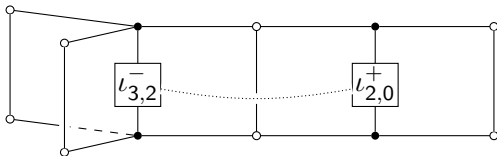
$$\uparrow$$

$$X .$$

A cheap daimon.

Synchronisation

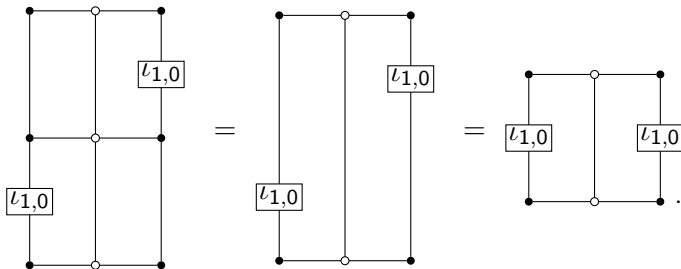
$$a.P \mid \bar{a}.Q \longrightarrow P \mid Q$$



Executions

Glueings of diagrams of the above kind together:

- horizontally,
- vertically (possibly denumerable).



Keeping track of the base position: $X \hookrightarrow U$.

A word on representing executions

- These diagrams: formalised as certain presheaves on a category \mathbb{C} .
- Basic diagrams: representables.
- Glueing = taking colimits.

More in the end if time permits.

The category \mathbb{E} of executions

- Objects: $X \hookrightarrow U$ well-formed.
- Morphisms: all commuting squares

$$\begin{array}{ccc}
 U & \longrightarrow & V \\
 \uparrow & & \uparrow \\
 X & \longrightarrow & Y.
 \end{array}$$

- Obvious functor $\pi: \mathbb{E} \rightarrow \mathbb{B}$:

$$(X \hookrightarrow U) \mapsto X,$$

where \mathbb{B} is the category of positions.

A Grothendieck topology

- We will now introduce a Grothendieck topology on \mathbb{E} .
- Whose canonical neighbourhoods will be **views**, in a sense very close to game semantics.

First we recall the definition of a Grothendieck topology.

Sieves

Definition

A **sieve** on an object U is

- a class of morphisms to U
- stable under precomposition by arbitrary morphisms.

Equivalently:

- A subpresheaf of the representable $\mathbb{E}(-, U)$.
- A subfibration of the domain fibration $\mathbb{E}/U \rightarrow \mathbb{E}$.

Grothendieck topologies

Definition

A **Grothendieck topology** J on \mathbb{E} assigns to each object U a class $J(U)$ of sieves satisfying

- 1 the total sieve $\mathbb{E}(-, U)$ is in $J(U)$;
- 2 if $S \in J(U)$ and $f: V \rightarrow U$, then $f^*(S) \in J(V)$;
(A covering sieve restricts to covering sieves on all opens.)
- 3 if $S \in J(U)$ and R is another sieve on U , then if for all $f: V \rightarrow U$ in S we have $f^*(R) \in J(V)$, then $R \in J(U)$.
(If a sieve covers all the opens of a covering sieve, then it is covering.)

Here $f^*(S) = \{g: W \rightarrow V \mid fg \in S\}$.

Our Grothendieck topology

Let \star have dimension 0, n have dimension 1, and so on up to 3.

Definition

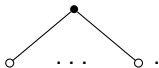
Let a sieve S on $X \hookrightarrow U$ in \mathbb{E} be **view-covering** when it is jointly surjective in dimensions 1 and 2.

- Apart from unused channel names, this also implies surjectivity in dim 0.
- Let's get to views.

Representable sequents

A **representable sequent**, denoted by n is a position with

- one player,
- knowing n names:



Elementary views

Definition

An *elementary view* V from n to n' is a cospan $n \hookrightarrow V \leftarrow n'$ isomorphic to a composite of

- a move M from a representable sequent n ,
- followed by a restriction to a representable sequent n' ,

i.e., a cospan of the shape

$$n \hookrightarrow M \leftarrow X \leftarrow n'.$$

Views

Definition

A *view* is a possibly denumerable (vertical) composition of elementary views in $\text{Cospan}(\widehat{\mathbb{C}})$.

Examples.

Views form a canonical covering

Proposition

For any execution $X \hookrightarrow U$, the sieve generated by morphisms from views into U is covering.

Proposition

Any covering sieve contains all morphisms from views.

Sheaves on a site

Let \mathbb{E} be equipped with a Grothendieck topology J .

Definition

A presheaf F is a **sheaf** when for any sieve S covering U , precomposition by $S \hookrightarrow U$ yields a bijection

$$\widehat{\mathbb{E}}(U, F) \cong \widehat{\mathbb{E}}(S, F).$$

Let $\text{Sh}(\mathbb{E})$ the full subcategory of such.

$$\begin{array}{ccc} U & \dashrightarrow & F \\ \uparrow & \nearrow & \\ S & & \end{array}$$

(Notation: $U = \mathbb{E}(-, U)$.)

(Being defined on the opens in S is enough.)

Relativising to a base position X

Definition

Let $(\mathbb{E})_X$ have

- as objects $U \leftrightarrow Y \rightarrow X$, with $Y \hookrightarrow U$ well-formed, and
- as morphisms commuting diagrams

$$\begin{array}{ccc}
 U & \longrightarrow & U' \\
 \updownarrow & & \updownarrow \\
 Y & \longrightarrow & Y' \\
 & \searrow & \swarrow \\
 & X &
 \end{array}$$

$(\mathbb{E})_X$ inherits a Grothendieck topology from \mathbb{E} .

Strategies as sheaves

Definition

Let the category S_X of **strategies** on X be $\text{Sh}((\mathbb{E})_X)$.

Intuition: a strategy S specifies for each execution $E \in (\mathbb{E})_X$ a number of **ways** for it to accept E .

Restriction to a subposition

- Consider $Y \rightarrow X$, and a strategy $S \in S_X$.
- Let $S|_Y$ send $U \leftrightarrow Z \rightarrow Y$ to

$$S(U \leftrightarrow Z \rightarrow Y \rightarrow X).$$

- This extends to morphisms.

Proposition

This forms a functor $S: \mathbb{B}^{op} \rightarrow \text{CAT}$.

The stack of strategies

Proposition

*This functor $S: \mathbb{B}^{op} \rightarrow \text{CAT}$ is a **stack** for the “surjective in dim 1” topology on \mathbb{B} .*

- Stacks are like sheaves but one dimension up.
- For sheaves: a bijection $\widehat{\mathbb{E}}(U, F) \cong \widehat{\mathbb{E}}(S, F)$.
- For stacks: an equivalence of categories.
- Kown fact: sheaves on slices form a stack.
- Here: mild generalisation.
- Why stacks? Intuitively, only the number of possible states should matter, not the precise set of states.

Canonical covering in \mathbb{B}

Proposition

For a given position X , the collection of morphisms $n \rightarrow X$ (for all n) is covering in \mathbb{B} .

Proposition

Any covering contains it.

Canonical covering continued

For any square

$$\begin{array}{ccc} Y & \longrightarrow & n \\ \downarrow & & \downarrow x \\ m & \xrightarrow{x'} & X \end{array}$$

with $x \neq x'$, Y has dimension 0.

Canonical covering continued

Proposition

If Y has $\dim 0$, then $S_Y \simeq 1$.

Indeed:

- any execution U on Y is covered by the empty family,
- which has a unique $\emptyset \rightarrow F$ for any sheaf F ,
- so $F(U) \cong 1$, which determines F up to iso.

Canonical spatial decomposition

Let $\text{Sq}(X) = \coprod_n X(n)$.

Proposition

$$S_X \simeq \prod_{(n,x) \in \text{Sq}(X)} S_n.$$

Temporal decomposition

- Let \mathcal{M}_X be the set of possible moves from X (explain the size).
- For each $i \in \mathcal{M}_X$, let X_i be the domain of the corresponding move.
- For any \mathbb{C} , let $\text{Fam}(\mathbb{C})$ denote the category with
 - ▶ objects families $f: X \rightarrow \text{ob } \mathbb{C}$,
 - ▶ morphisms $f \rightarrow g$ the pairs of
 - ▶ $u: X \rightarrow Y$ such that $gu = f$, and
 - ▶ $v: X \rightarrow \mathbb{C}_1$ with

$$\text{dom } v(x) = f(x) \qquad \text{cod}(v(x)) = g(u(x)).$$

Examples.

Temporal decomposition

Theorem

Equivalence of categories: $S_n \simeq \text{Fam} \left(\prod_{i \in \mathcal{M}_n} S_{X_i} \right)$.

A strategy is determined by

- its initial states, and
- what remains of them after each possible move.

Almost a sketch: would be a bijection of sets

$$S_n \cong \prod_{i \in \mathcal{M}_n} S_{X_i}.$$

Scenarios

In concurrency,

- Physical, or **fair** scenario: players are really independent;
- Interpreted, or **potentially unfair** scenario: a scheduler is responsible for parallelism.

Must testing

Supposing a fixed move \heartsuit :

Definition

A process P is **must orthogonal** to a context C , when all maximal traces of $C[P]$ play \heartsuit at some point.

Notation: $P \perp^m C$, $P \perp^m$.

Definition

P and Q are **must equivalent**, notation $P \sim_m Q$, when

$P \perp^m = Q \perp^m$.

Must testing in an unfair setting

Usually, only the unfair scenario is formalised:

$$P = (\Omega \mid \bar{a}) \quad \text{and} \quad Q = \Omega$$

are must equivalent.

The obvious test $C = a.\heartsuit \mid \square$ is not orthogonal to P .

Indeed, there is an infinite looping trace, maximal.

Fair testing in an unfair setting

- The example

$$(\Omega \mid \bar{a}) \sim_m \Omega$$

takes potential unfairness of the scheduler into account.

- Usually people do not want to, and resort to:

Definition

A process P is **fair orthogonal** to a context C , when all finite traces of $C[P]$ extend to traces that play \heartsuit at some point.

Notation: $P \perp^f C$, $P \perp^f$.

Definition

P and Q are **fair equivalent**, notation $P \sim_f Q$, when $P \perp^f = Q \perp^f$.

Solves the issue.

Closed-world observations

Definition

An observation $X \hookrightarrow U$ is **closed-world** when both

$$\prod_{n,i} U(\iota_{n,i}^+) \xleftarrow{\epsilon} \prod_{n,i,m,j} U(\tau_{n,i,m,j}) \xrightarrow{\rho} \prod_{n,i} U(\iota_{n,i}^-) \quad (1)$$

are surjective.

Global behaviours

- Let $\mathbb{W} \hookrightarrow \mathbb{E}$ be the full subcategory of closed-world observations.
- Let $\mathbb{W}(X)$ be the fibre over X for the projection functor $\mathbb{W} \rightarrow \mathbb{B}$.

Definition

Let the category of **global behaviours** on X be simply $G_X = \widehat{\mathbb{W}(X)}$.

- Cf. Joyal, Nielsen, and Winskel.
- The inclusion $\mathbb{W}(X) \hookrightarrow (\mathbb{E})_X$ induces a functor $G_I: S_X \rightarrow G_X$.

Observable criterion

Definition

An **observable criterion** consists for all positions X , of a subcategory $\perp_X \hookrightarrow G_X$.

Interactive equivalence

Definition

For any strategy S on X and any pushout P

$$\begin{array}{ccc}
 I & \longrightarrow & Y \\
 \downarrow & & \downarrow \\
 X & \longrightarrow & Z
 \end{array}
 \quad (2)$$

of positions with I of dimension 0, let $S^{\perp P}$ be the class of all strategies T on Y such that $\text{Gl}(S \parallel T) \in \perp_Z$.

- Here \parallel denotes amalgamation in the stack S .
- Let us make this concrete.

Fair testing

Definition

A closed-world execution is *successful* when it contains a \heartsuit_n .

Definition

Given a global behaviour $G \in G_X$, an *extension* of a state $s \in G(U)$ to U' is an $s' \in G(U')$ with $i: U \rightarrow U'$ and $s' \cdot i = s$.

Definition

The *fair* criterion $\perp\!\!\!\perp_X^f$ contains all global behaviours G such that any state $s \in G(U)$ for finite U admits a successful extension.

Must testing

Definition

An extension of $s \in G(U)$ is **strict** when $U \rightarrow U'$ is not surjective.

Definition

For any global behaviour $G \in G_X$, a state $s \in G(U)$ is **G -maximal** when it has no strict extension.

Definition

Let the **must** criterion $\perp\!\!\!\perp_X^m$ consist of all global behaviours G such that for all closed-world U , and G -maximal $s \in G(U)$, U is successful.

The key result

Theorem

For any strategy S , any state $s \in \text{Gl}(S)(U)$ admits a $\text{Gl}(S)$ -maximal extension.

Fair vs. must

Thanks to the theorem, we have:

Lemma

For all $S \in S_X$, $\text{Gl}(S) \in \perp_X^m$ iff $\text{Gl}(S) \in \perp_X^f$.

Proof.

Let $G = \text{Gl}(S)$.

(\Rightarrow) By the theorem, any state $s \in G(U)$ has a G -maximal extension $s' \in G(U')$, for which U' is successful by hypothesis, hence s has a successful extension.

(\Leftarrow) Any G -maximal $s \in G(U)$ admits by hypothesis a successful extension which may only be on U by G -maximality, and hence U is successful. \square

Fair equals must

Theorem

For all $S, S' \in S_X$, $S \sim_m S'$ iff $S \sim_f S'$.

Proof.

(\Rightarrow) Consider two strategies S and S' on X , and a strategy T on Y (as in the pushout P). We have:

$$\begin{aligned} \text{Gl}(S \parallel T) \in \perp^f & \quad \text{iff } \text{Gl}(S \parallel T) \in \perp^m \\ & \quad \text{iff } \text{Gl}(S' \parallel T) \in \perp^m \\ & \quad \text{iff } \text{Gl}(S' \parallel T) \in \perp^f. \end{aligned}$$

(\Leftarrow) Symmetric. □

Perspectives

Short term:

- We have a translation of CCS processes into this model.
- Identify the equivalence induced by this translation.

Longer term:

- Treat π, λ, \dots
- Understand the abstract structure.
- What is a compilation?